

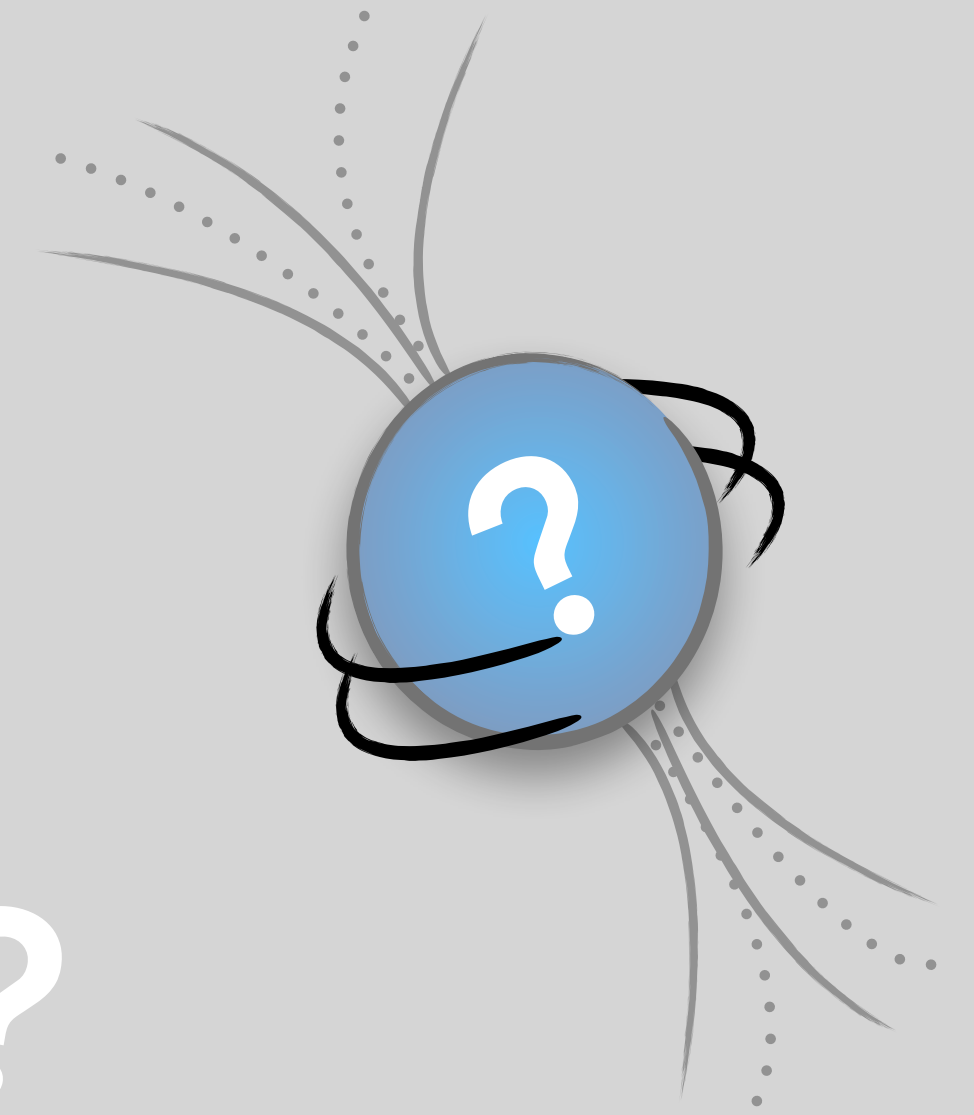
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Fundação
para a Ciência
e a Tecnologia



How can deep learning help us decipher neutron star composition



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19 March 2026

Young
Astronomers
Meet



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(Head)



Dr. Paweł Ciecieląg
(Independent Specialist)

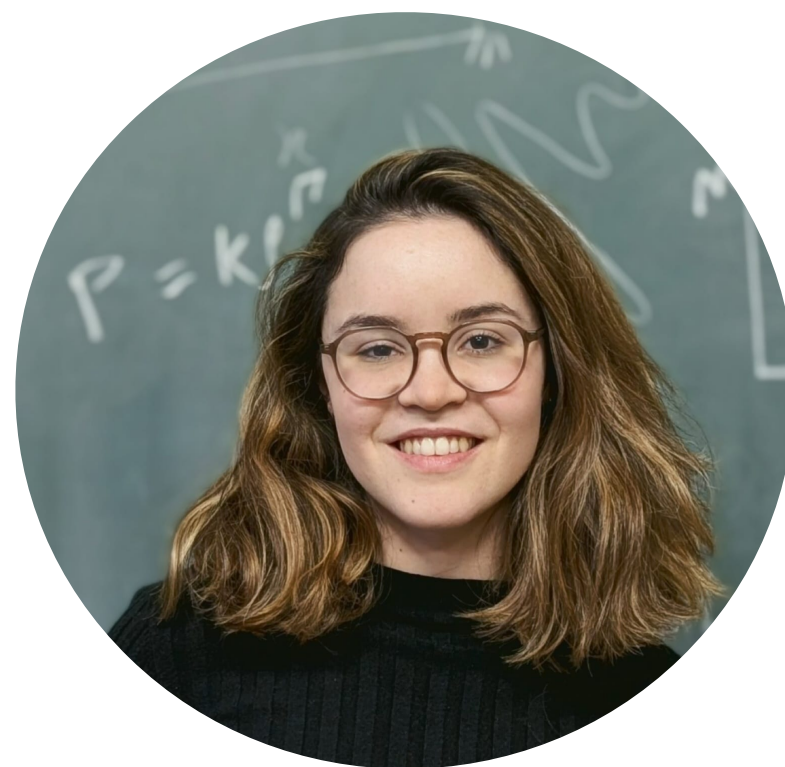


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(Postdoc)



Dr. Sreekanth Harikumar
(Postdoc)

CAMK GW group



Valéria Carvalho
(Visiting PhD student)



Sudhagar Suyamprakasam
(PhD student)



Anirudh Nemmani
(PhD student)

Outline

► Motivation:

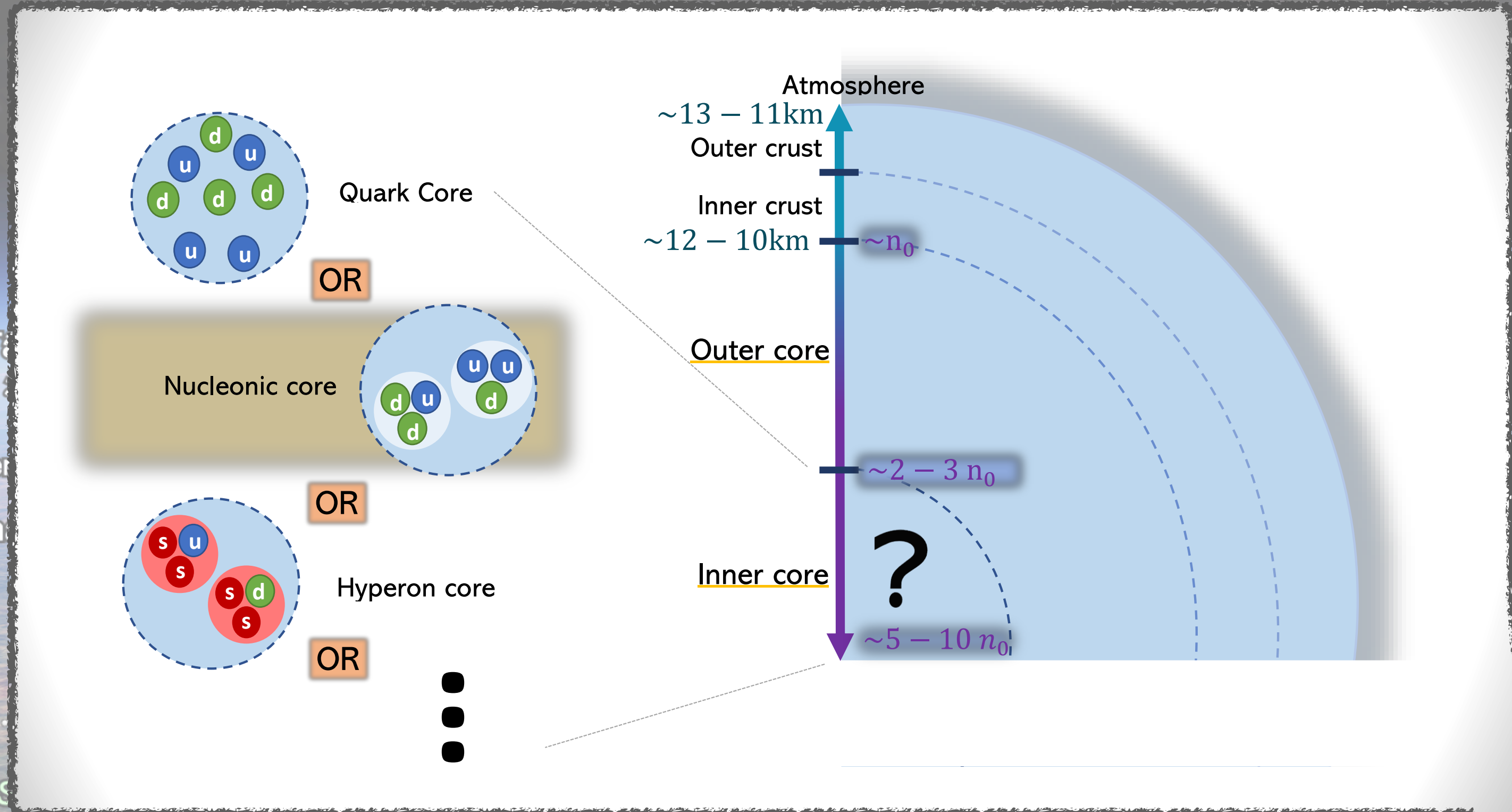
- What do we aim to study in neutron stars;
- What is deep learning;

► Example:

How effectively can Neural Posterior Estimation infer the Neutron Star Equation of State



What's inside a neutron star?



$$M = 1 \sim 2 M_{\odot}$$

$$R \approx 10^{-5} R_{\odot}$$

$$T = 0$$



The equation of state: A bridge between micro and macro

.....

Equation of State(EoS)

$$p(\varepsilon)$$

Speed of Sound

$$c_s^2(n) = \frac{dp(n)}{d\varepsilon(n)}$$

Trace Anomaly

$$\Delta(n) = \frac{1}{3} - \frac{p(n)}{\varepsilon(n)}$$

Tolman-Oppenheimer-Volkoff equations

$$\frac{dP(r)}{dr} = -\frac{\varepsilon(r)m(r)}{r^2} \left(1 + \frac{P(r)}{\varepsilon(r)}\right) \left(1 + \frac{4\pi r^3 P(r)}{m(r)}\right) \left(1 - \frac{2m(r)}{r}\right)^{-1}$$

$$\frac{dm(r)}{dr} = 4\pi r^2 \varepsilon(r)$$

Tidal deformability

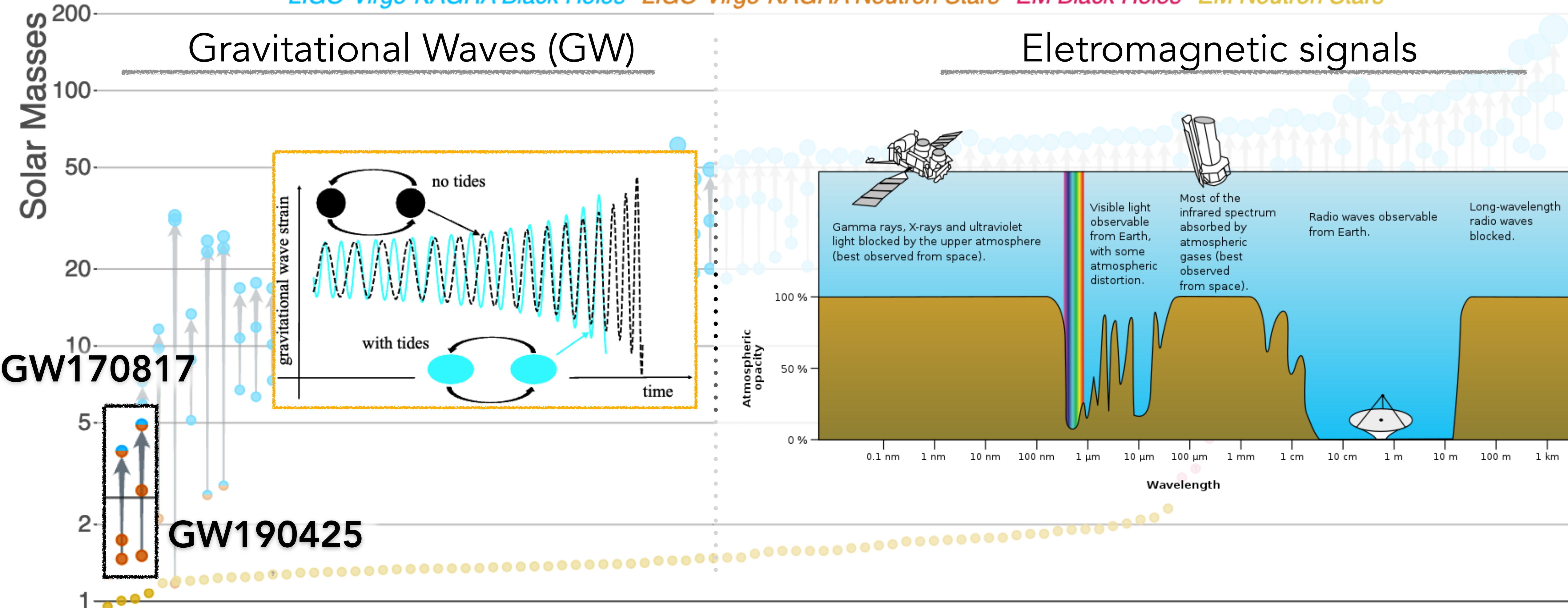
$$\Lambda = \frac{2}{3} k_2 C^{-5}, \quad C = \frac{M}{R}$$

Current observations

LIGO-Virgo-KAGRA Black Holes LIGO-Virgo-KAGRA Neutron Stars EM Black Holes EM Neutron Stars

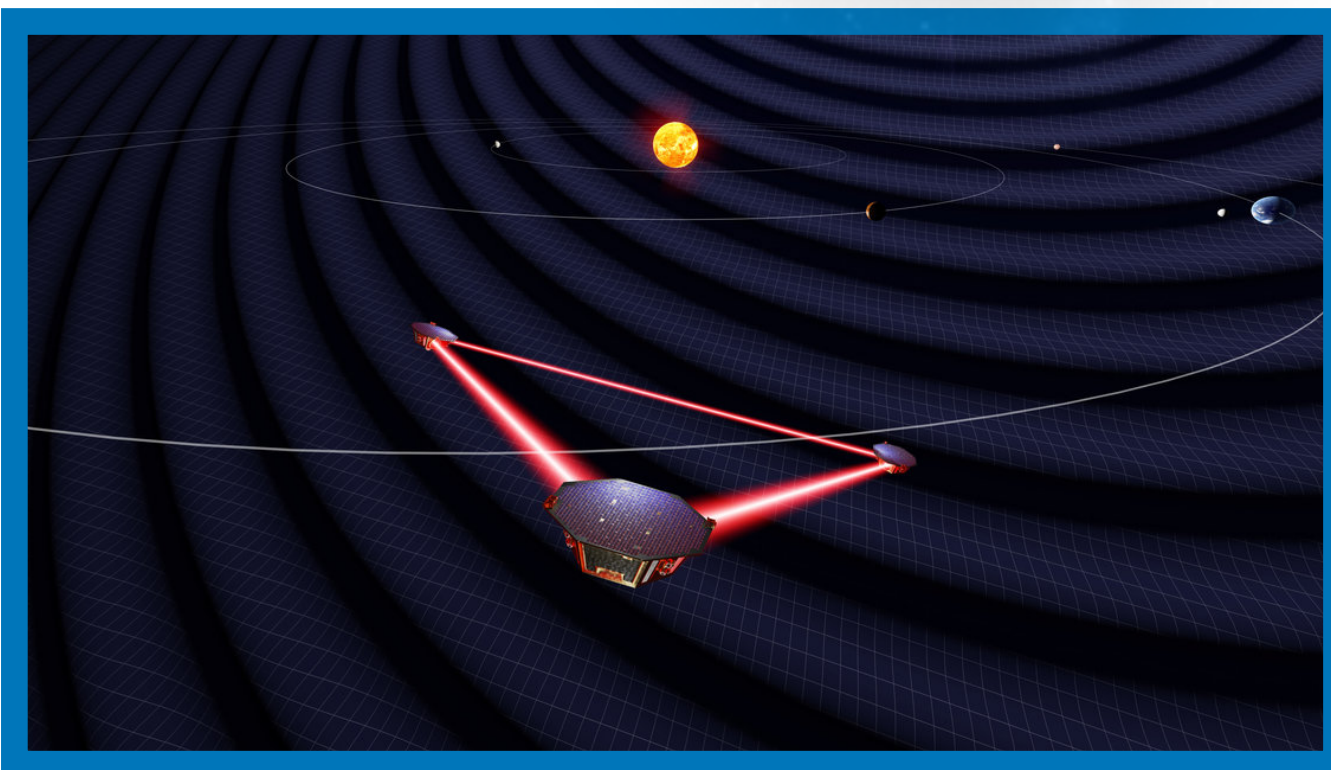
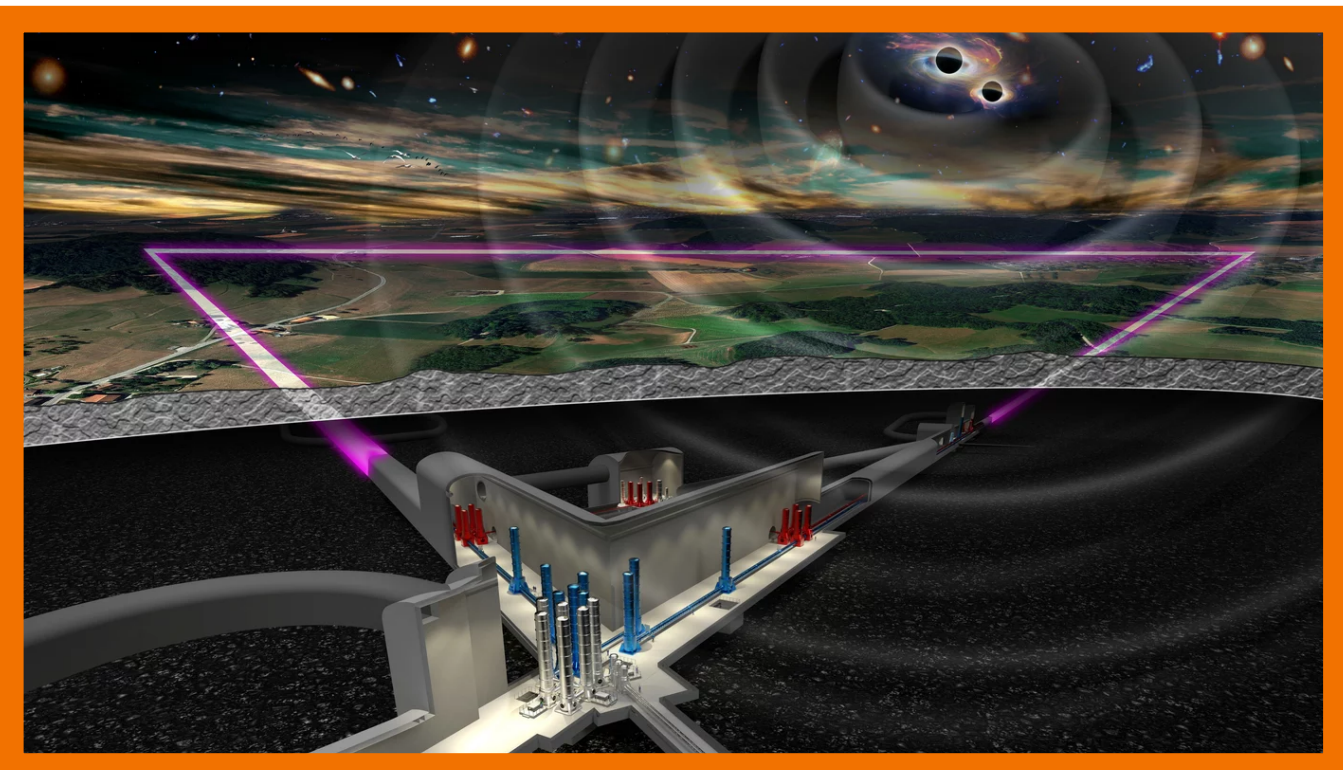
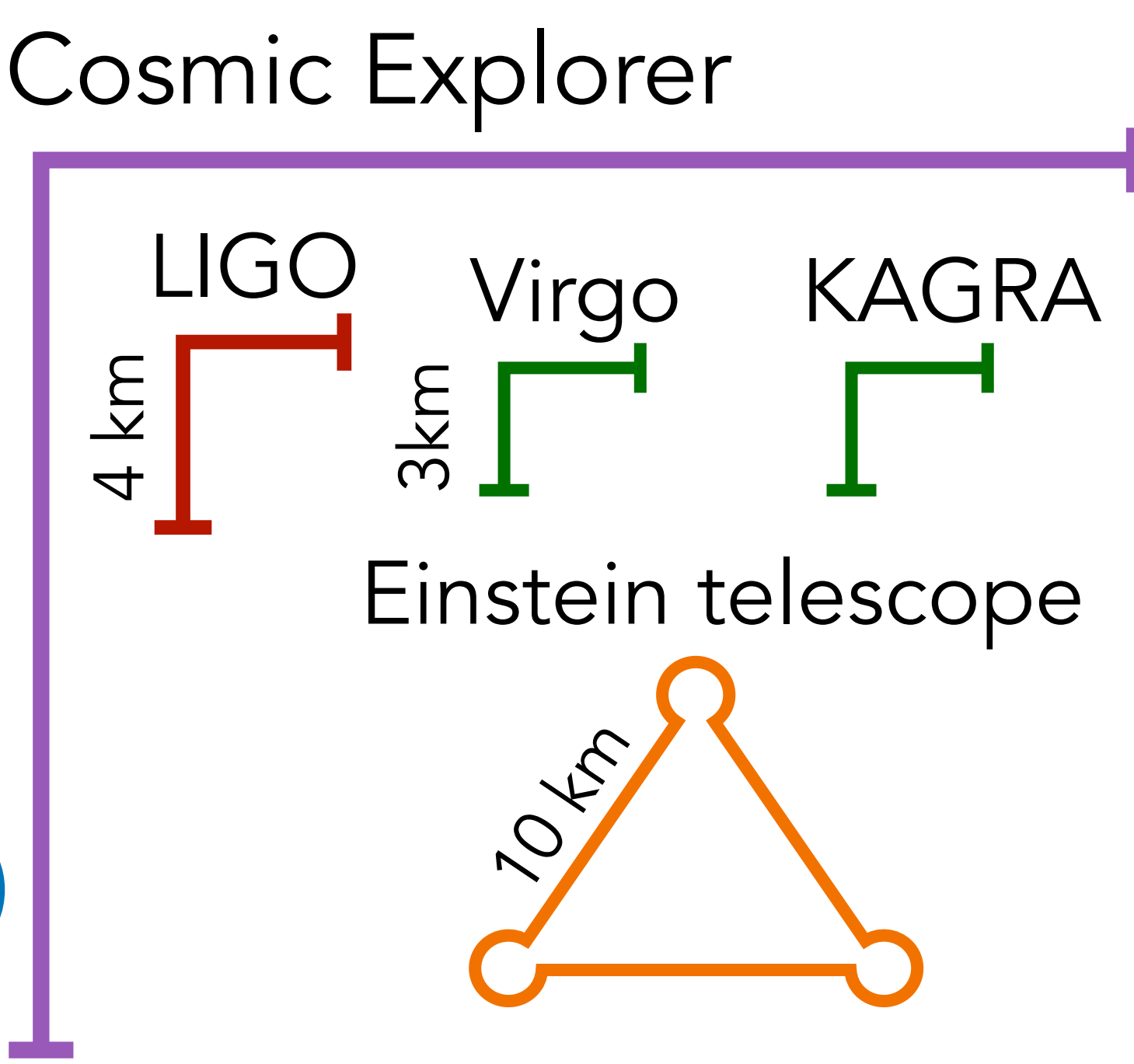
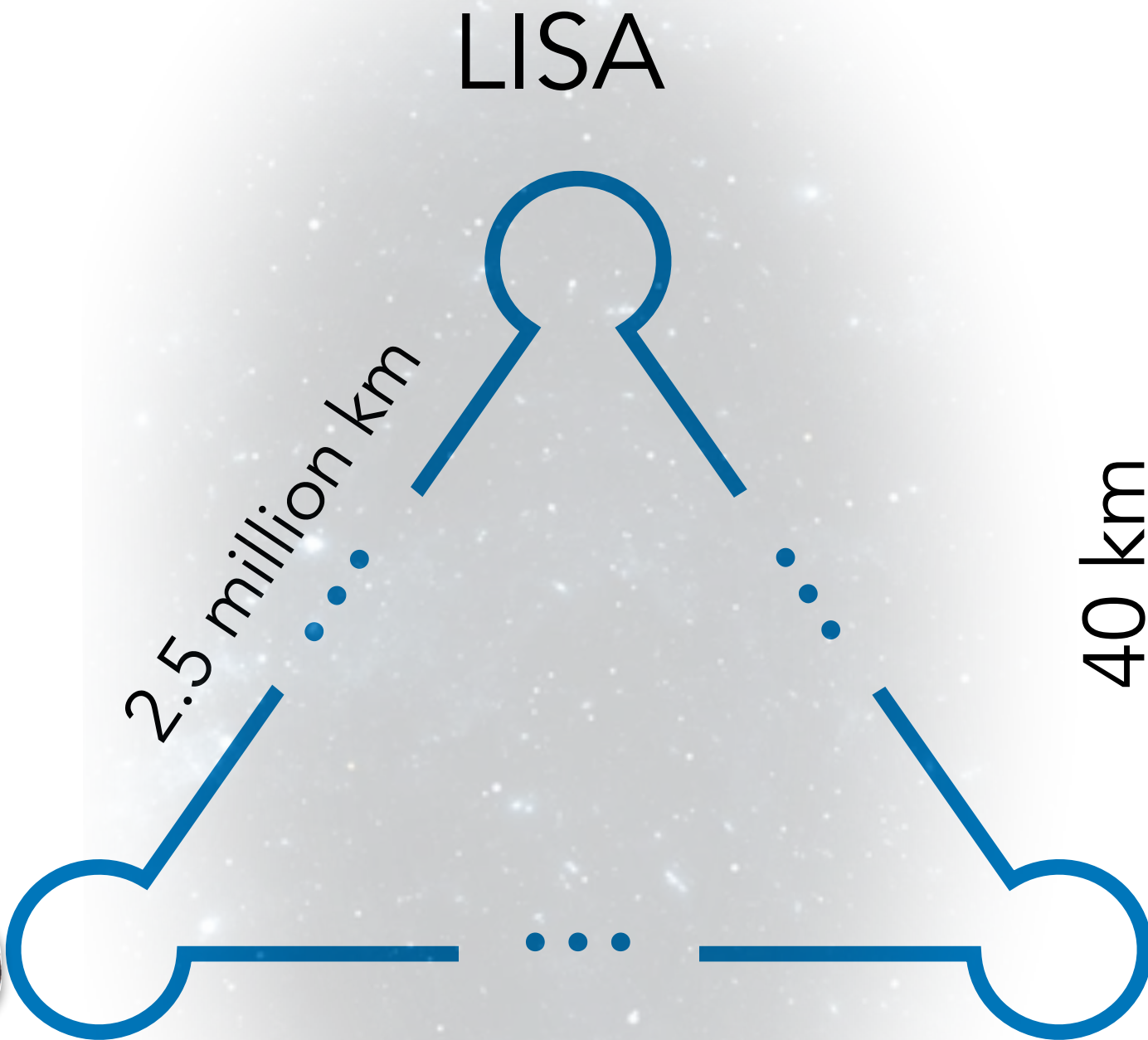
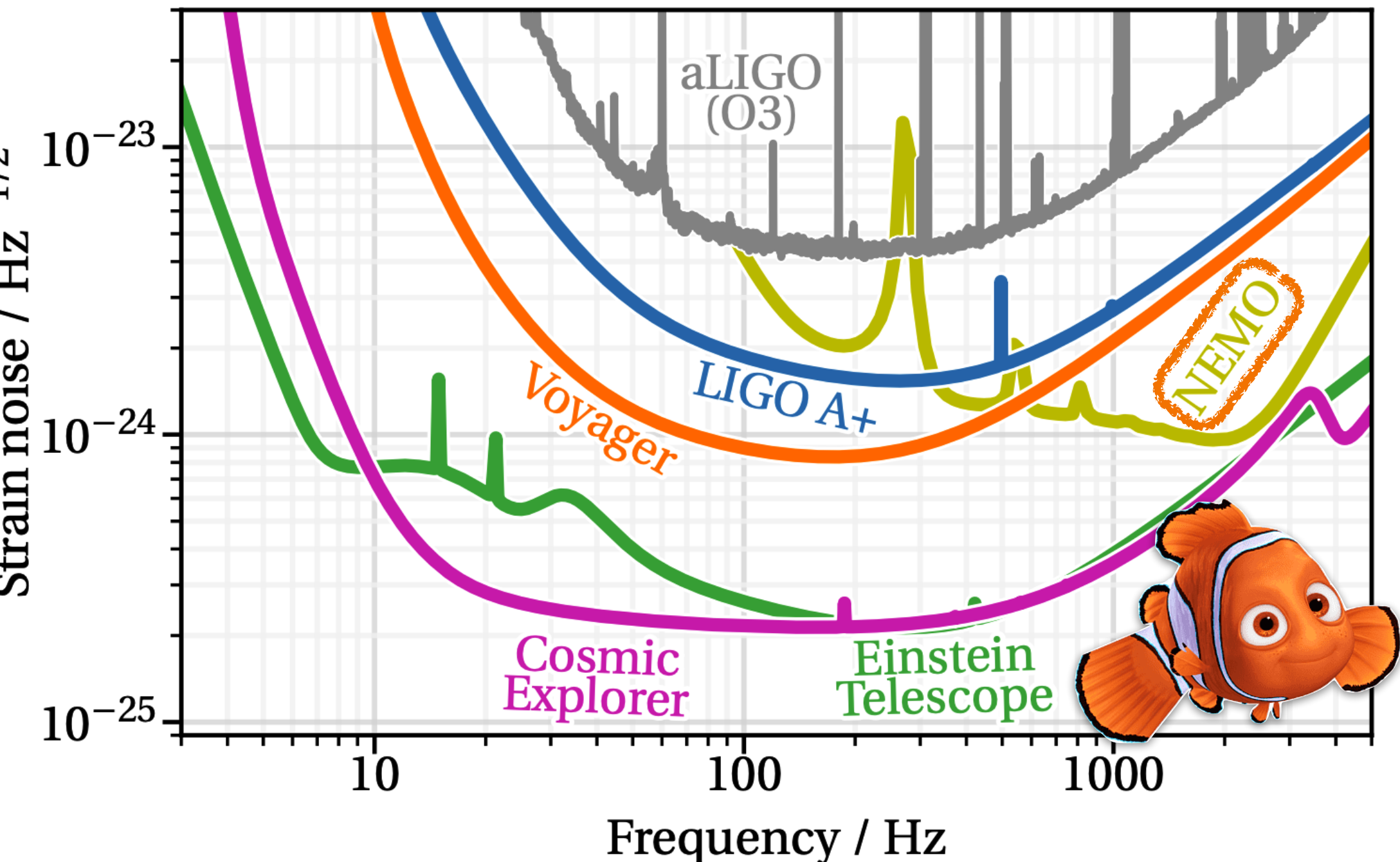
Gravitational Waves (GW)

Eletromagnetic signals

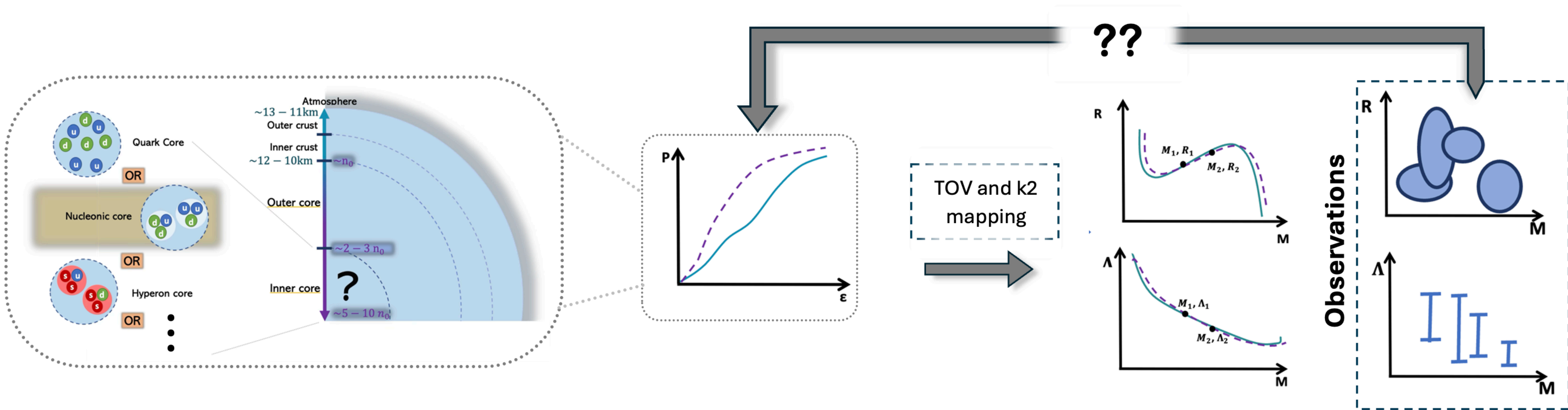


A golden age of data is coming- GW future detectors

© Cosmic Explorer



The challenge: A sparse and noisy inverse problem



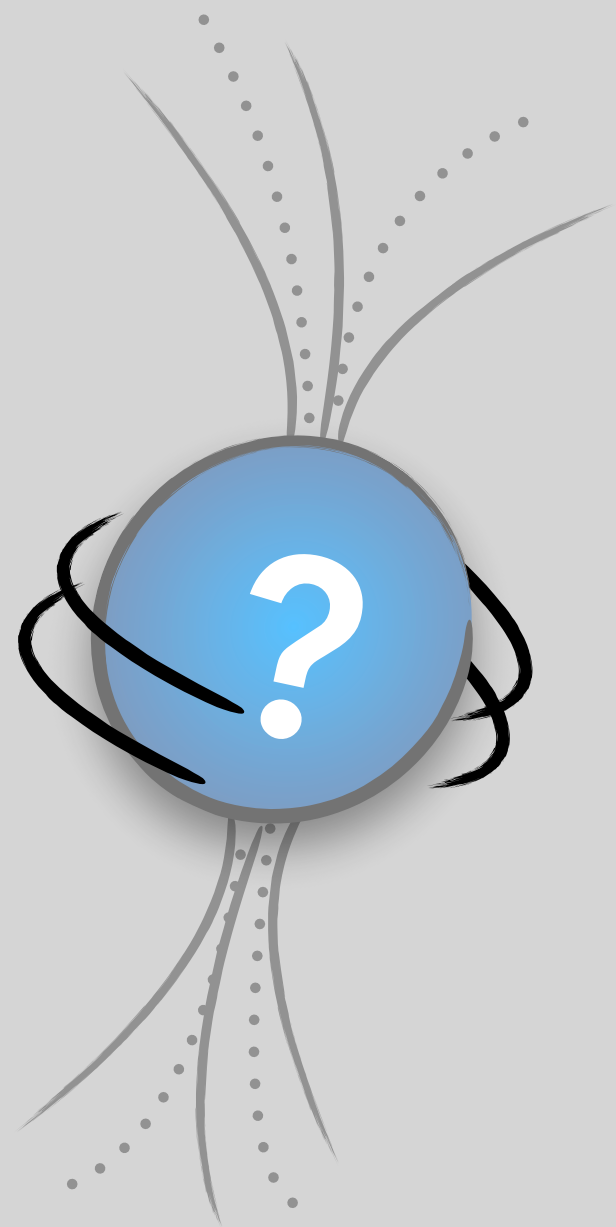
For current observations:

- ▶ Sparse coverage of observables,
- ▶ Uncertainties and degeneracies.

For future observations:

- ▶ Big amount of data,
- ▶ Smaller uncertainties, less degeneracies.

The solution, let's talk about deep learning



What is Deep Learning?



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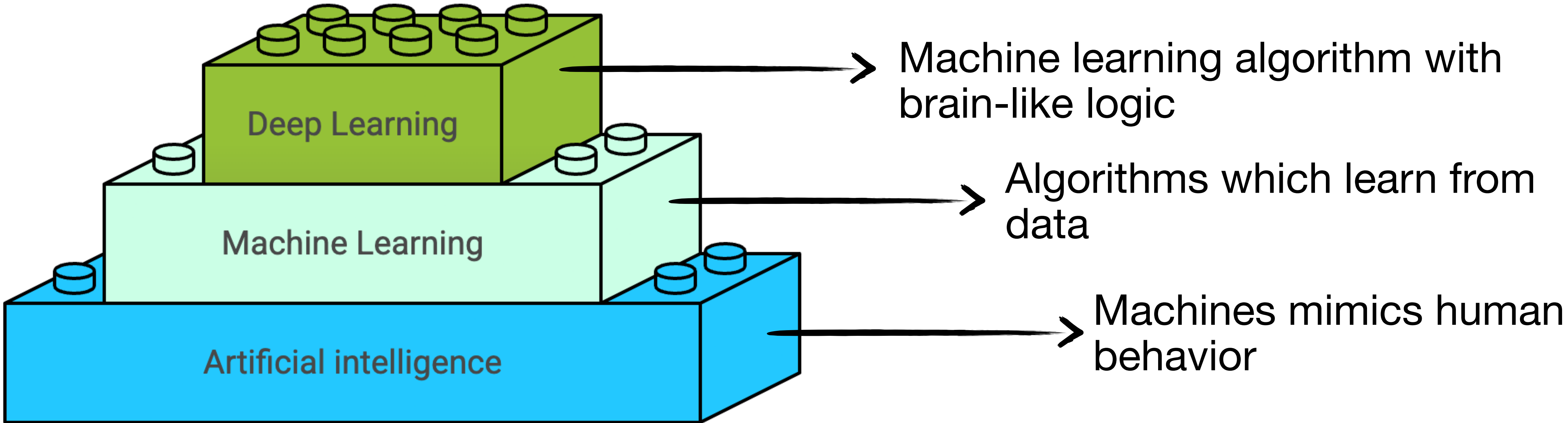


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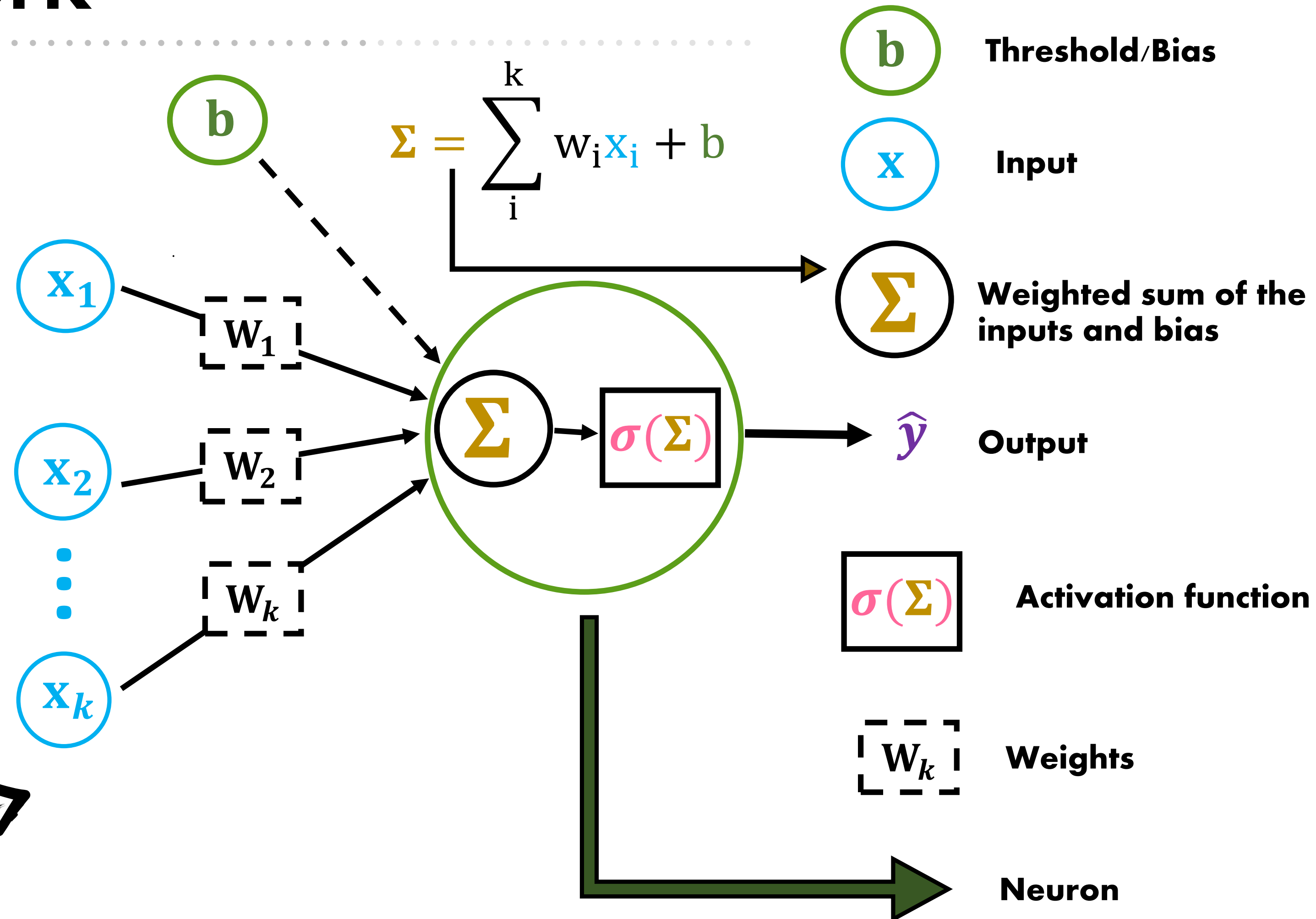
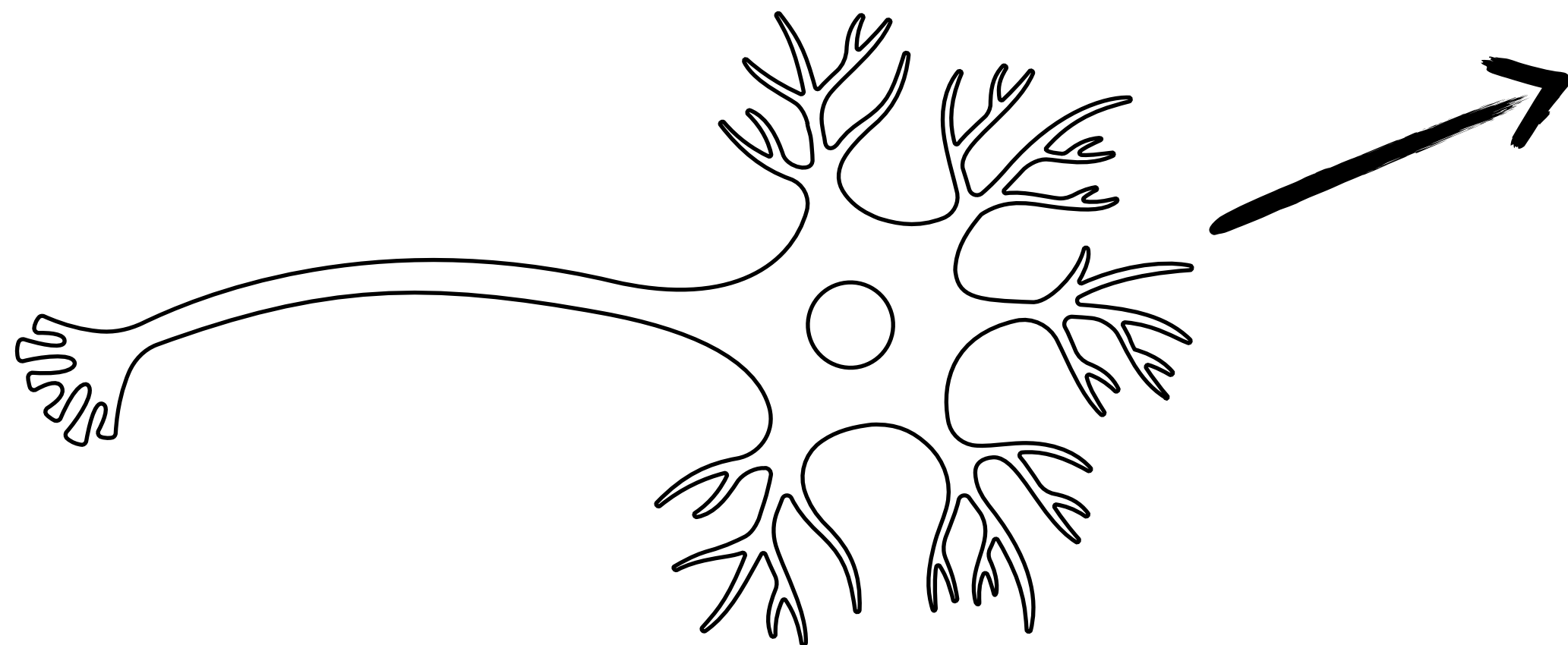
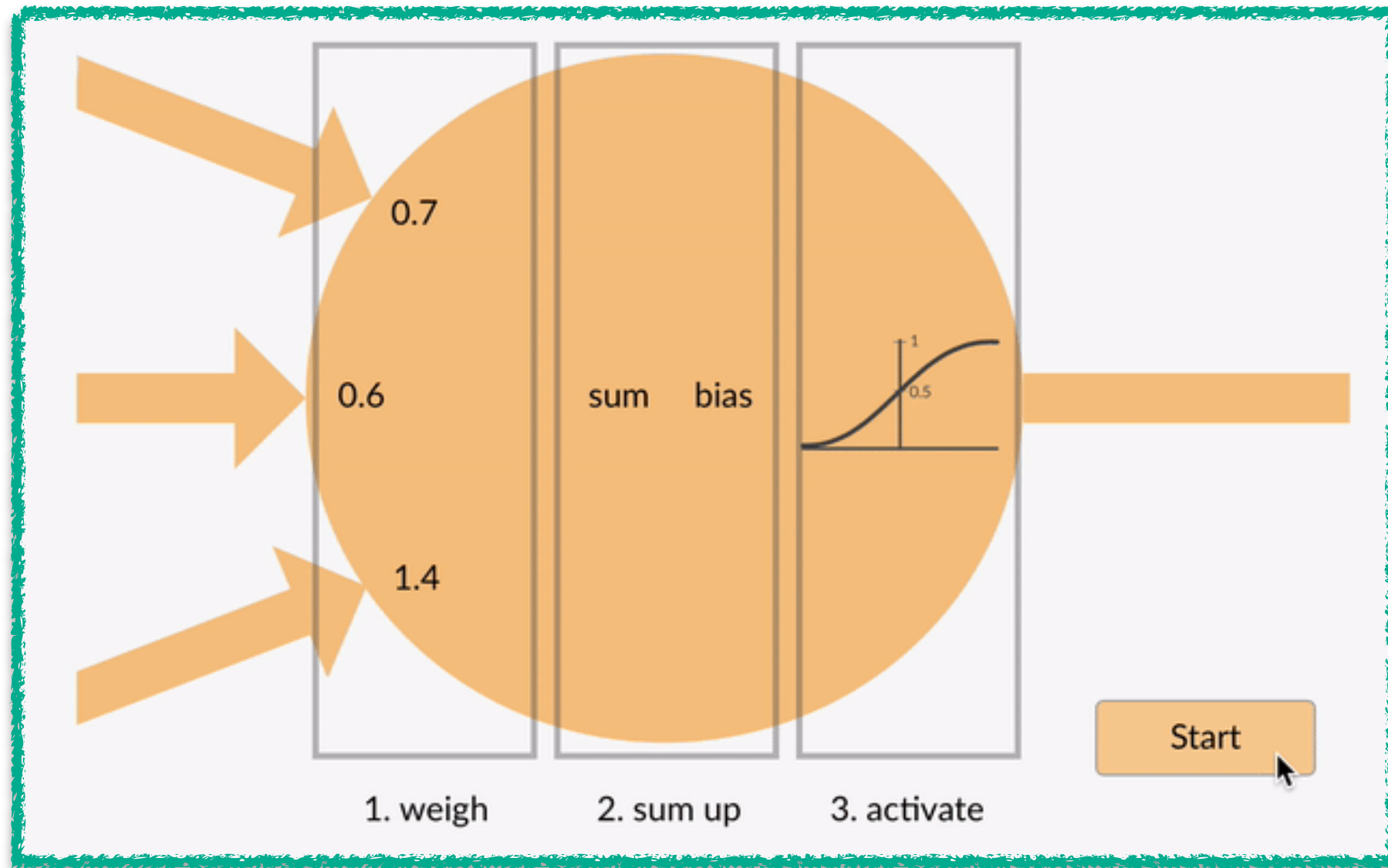


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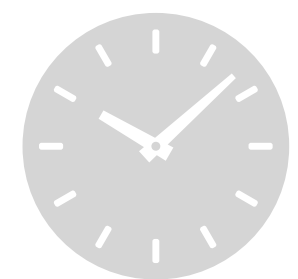
What is a Neural network



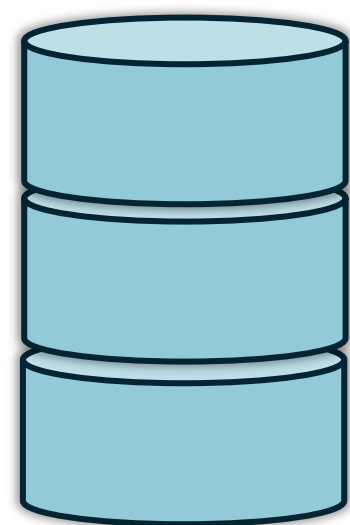
Deep Learning pipeline

Benefits :

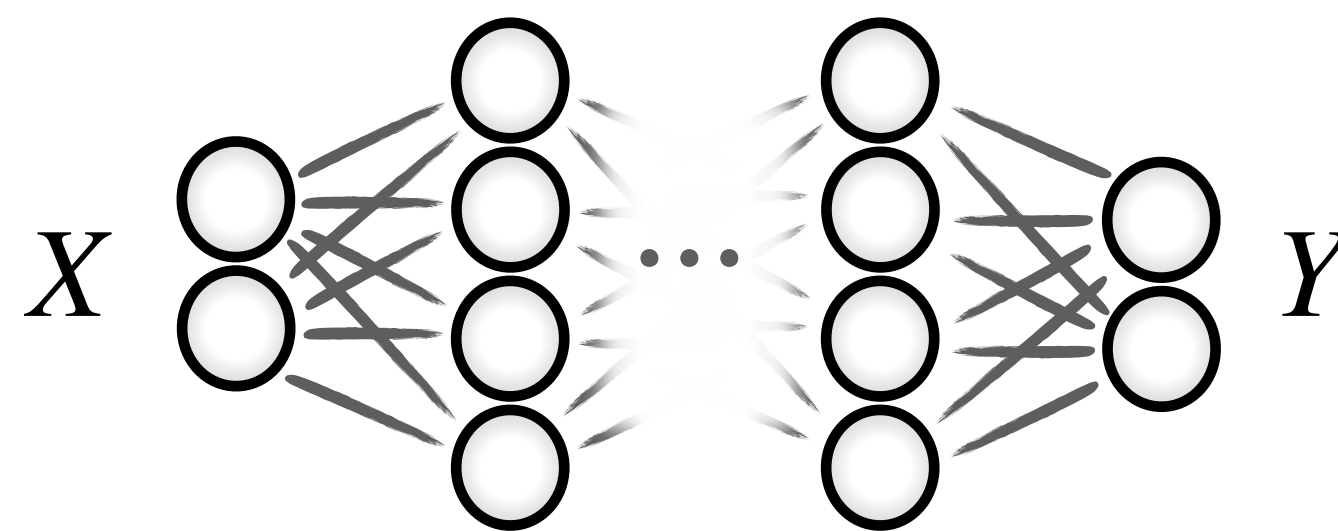
- ▶ Handles complexity,
- ▶ Extremely Fast,
- ▶ Quantifies Uncertainty.



≈ **70%**
Prepare data



28%
Build and train models

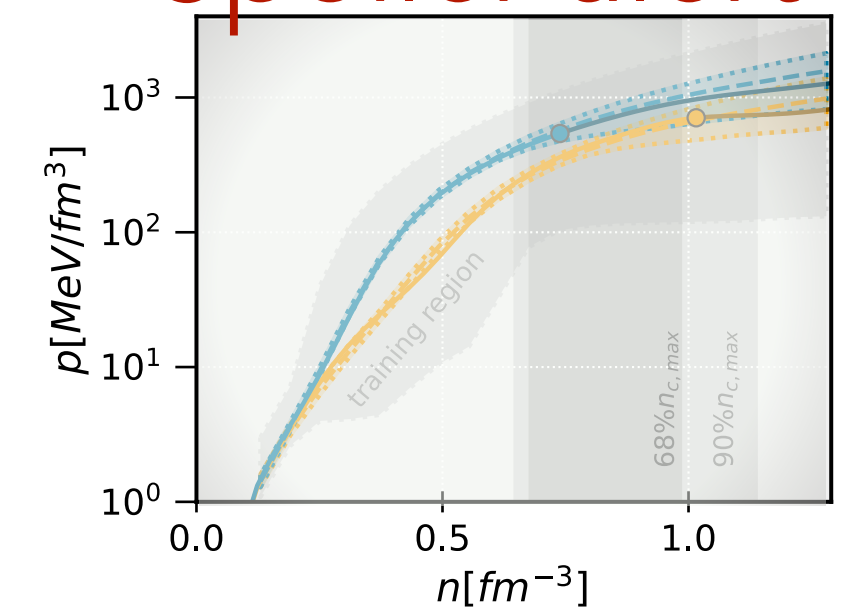


$$f_{\theta}(x) : X \rightarrow Y$$



2%
Deploy and predict

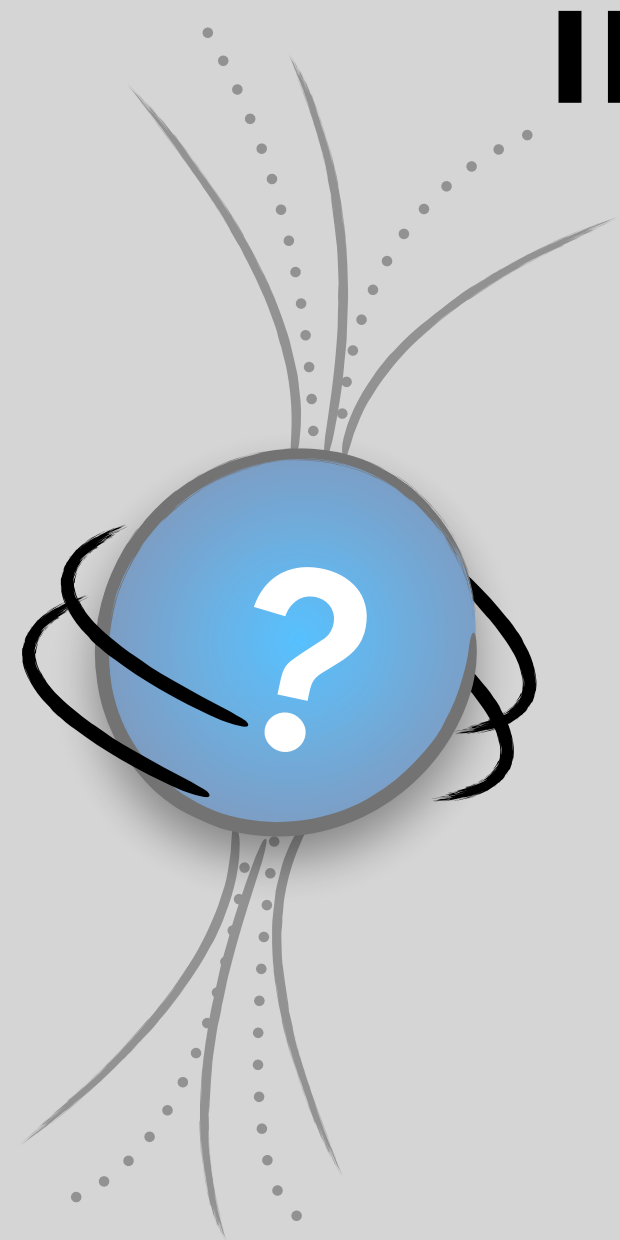
Spoiler alert !



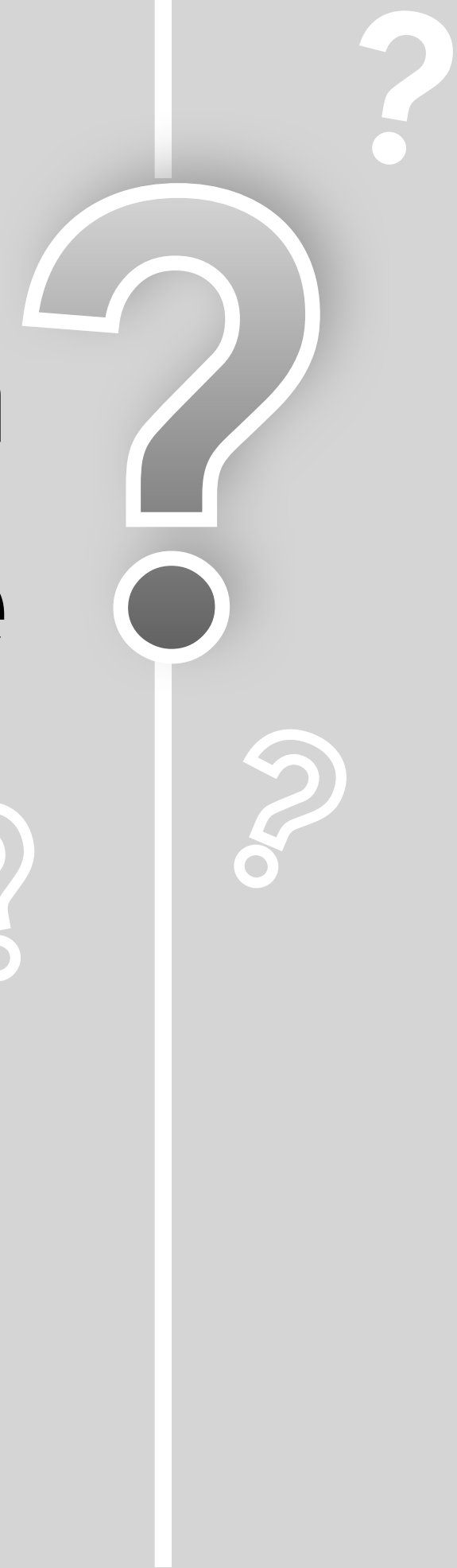


PRD 112,083044

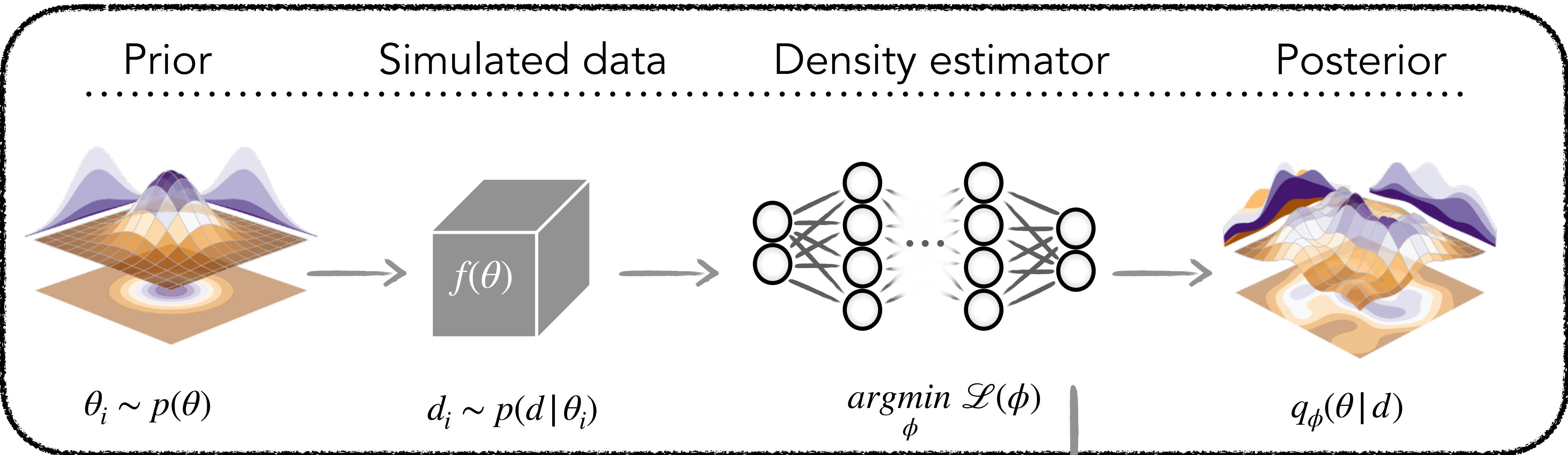
How effectively can Neural Posterior Estimation infer the Neutron Star Equation of State



How?

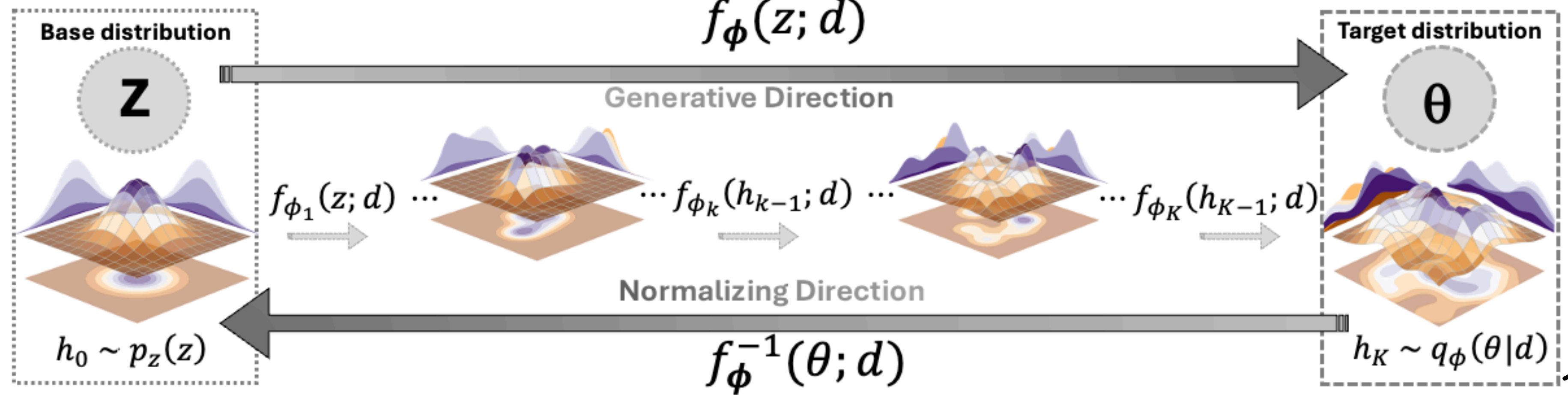


Neural posterior estimation



Conditional Normalizing Flows (CNF)

- Invertible
- Flexible
- Bijective



Quantities we aim to predict : $p(EoS | O)$

Two agnostic models :

Piecewise Polytopics (PT) PRD **111**,023035 (2025)

Gaussian Processes (GP) *Nat Commun* **14**, 8451 (2023)

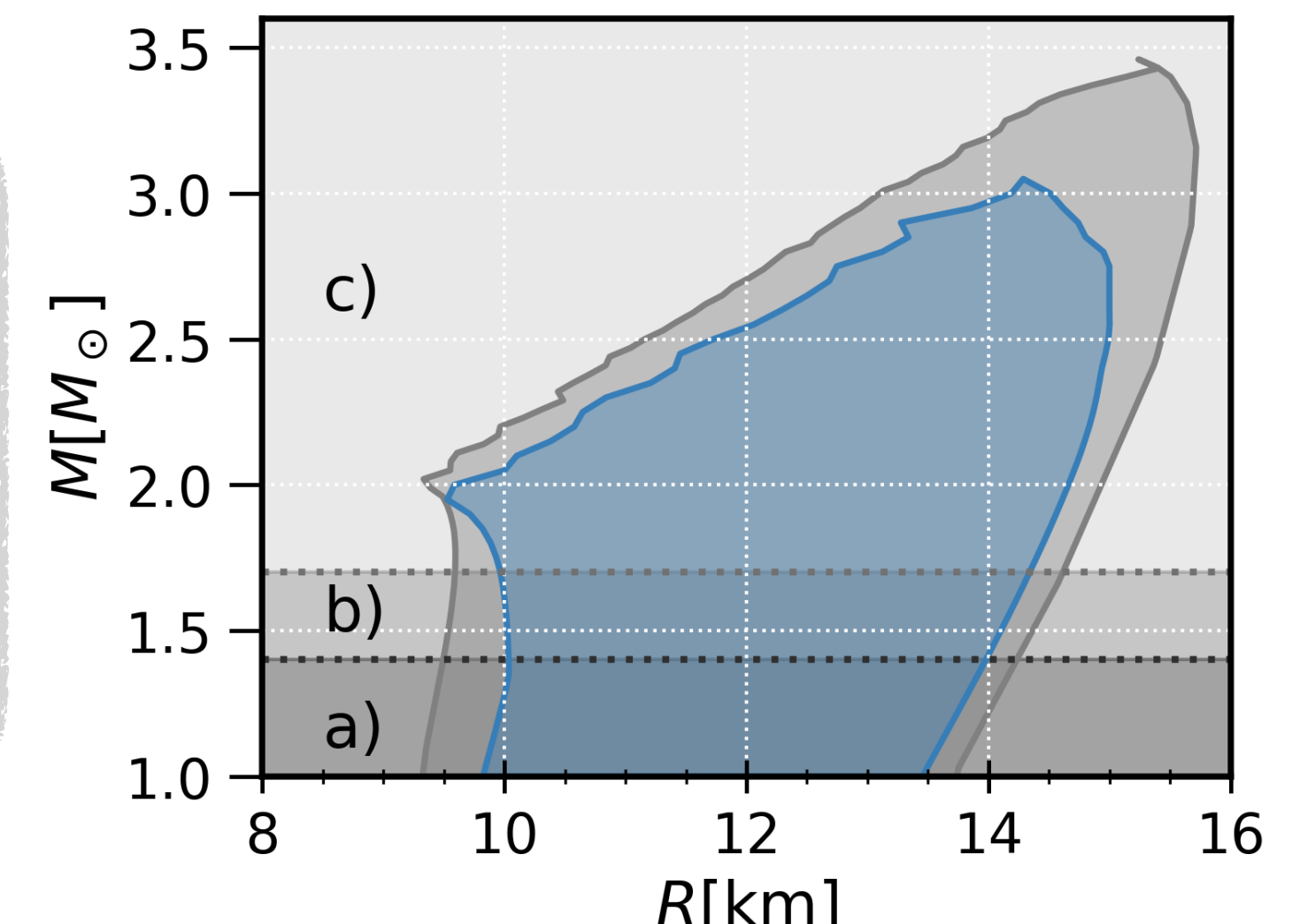
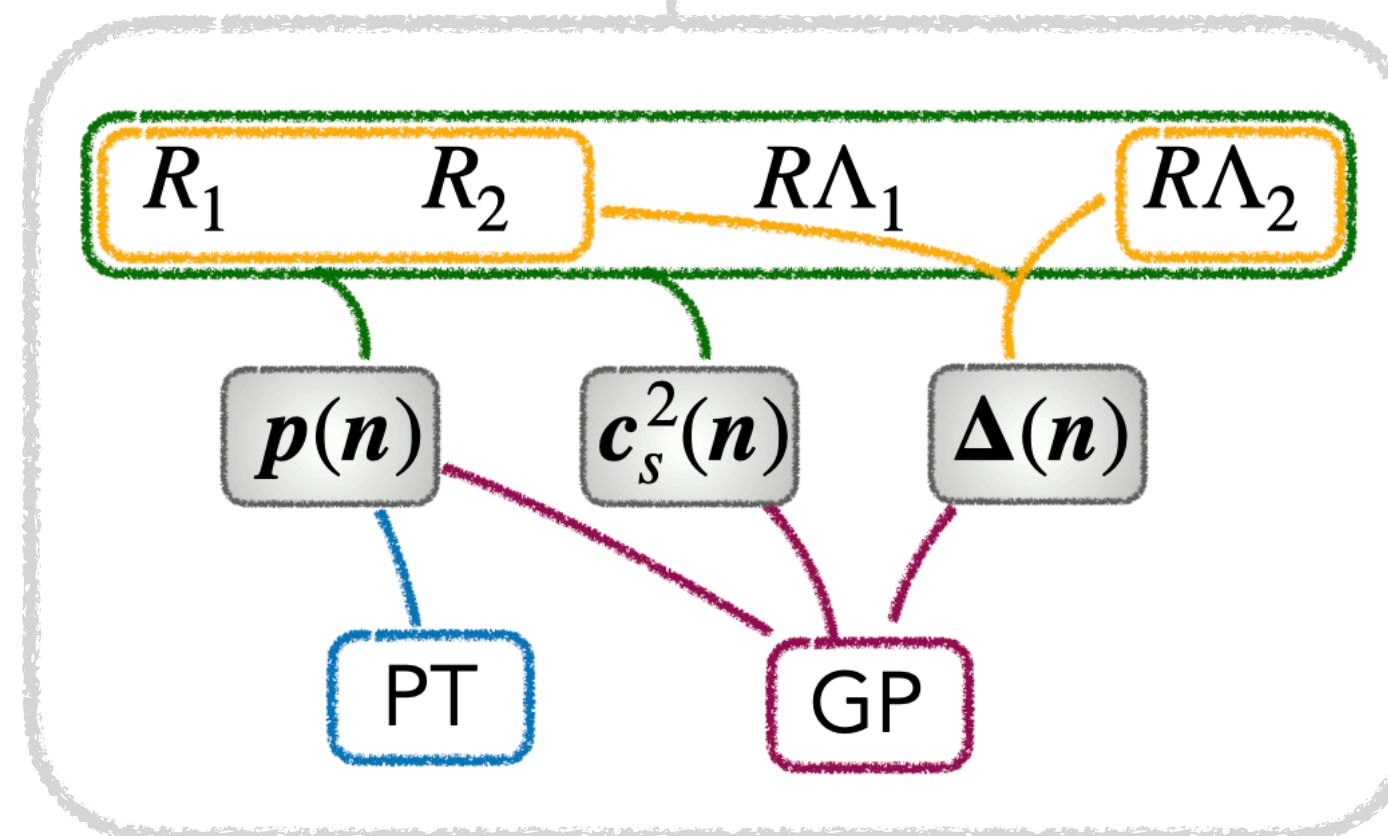
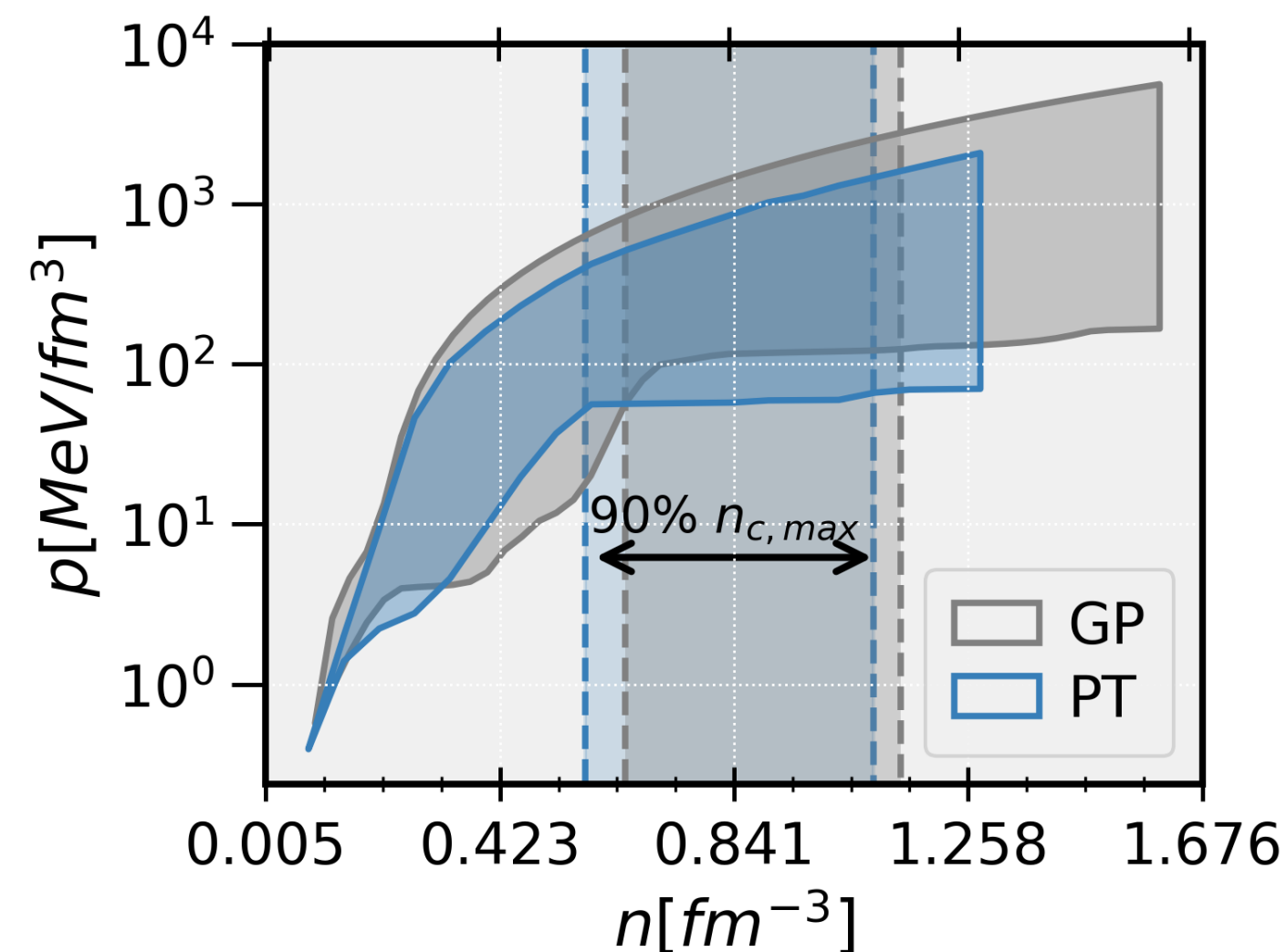
The predicted physical quantities :

$$\begin{cases} \mathbf{p}(\mathbf{n}) = [p(n_1), \dots, p(n_{20})], \\ \mathbf{c}_s^2(\mathbf{n}) = [c_s^2(n_1), \dots, c_s^2(n_{20})], \\ \mathbf{\Delta}(\mathbf{n}) = [\Delta(n_1), \dots, \Delta(n_{20})], \end{cases}$$




The conditioned quantities :

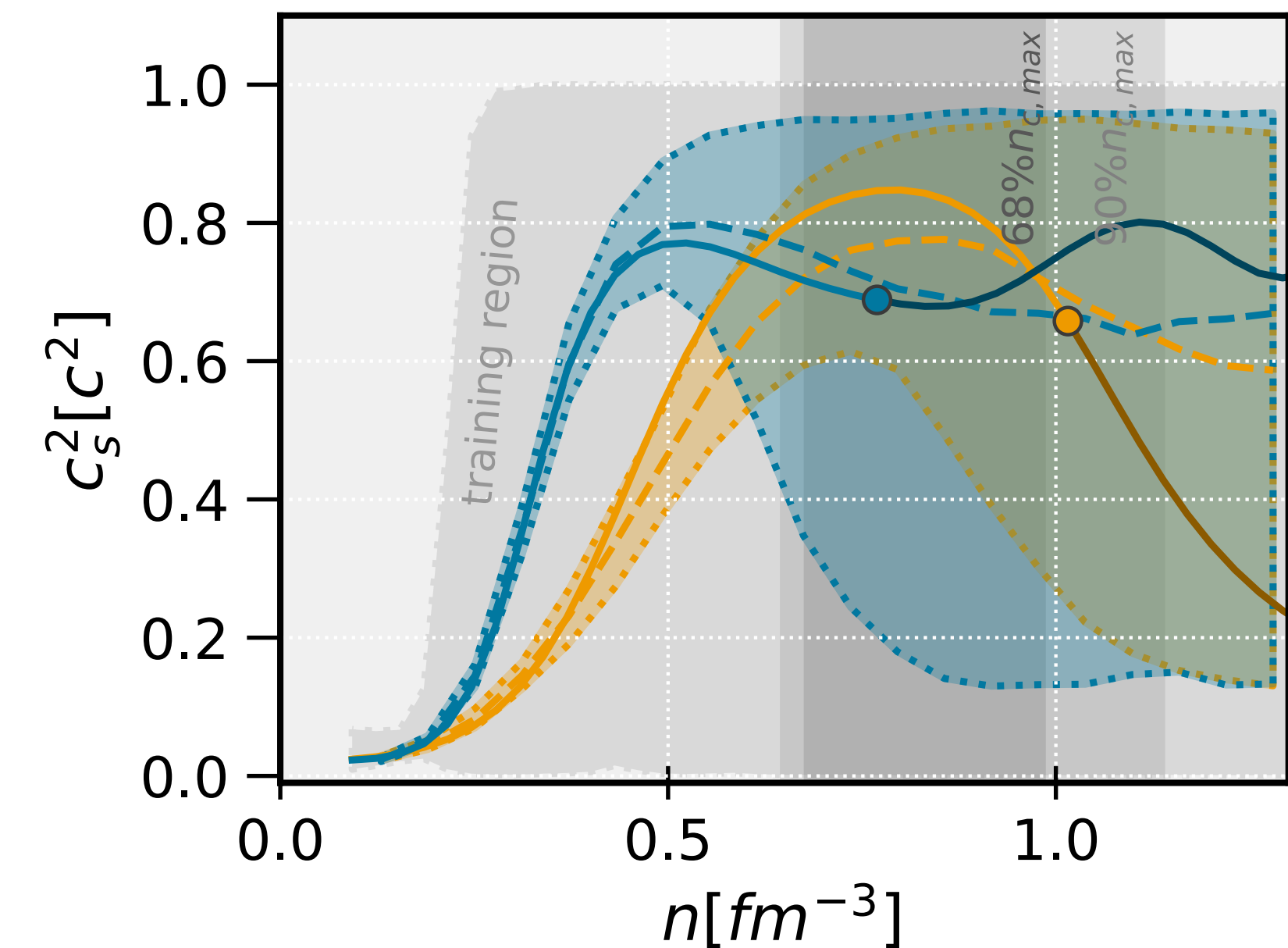
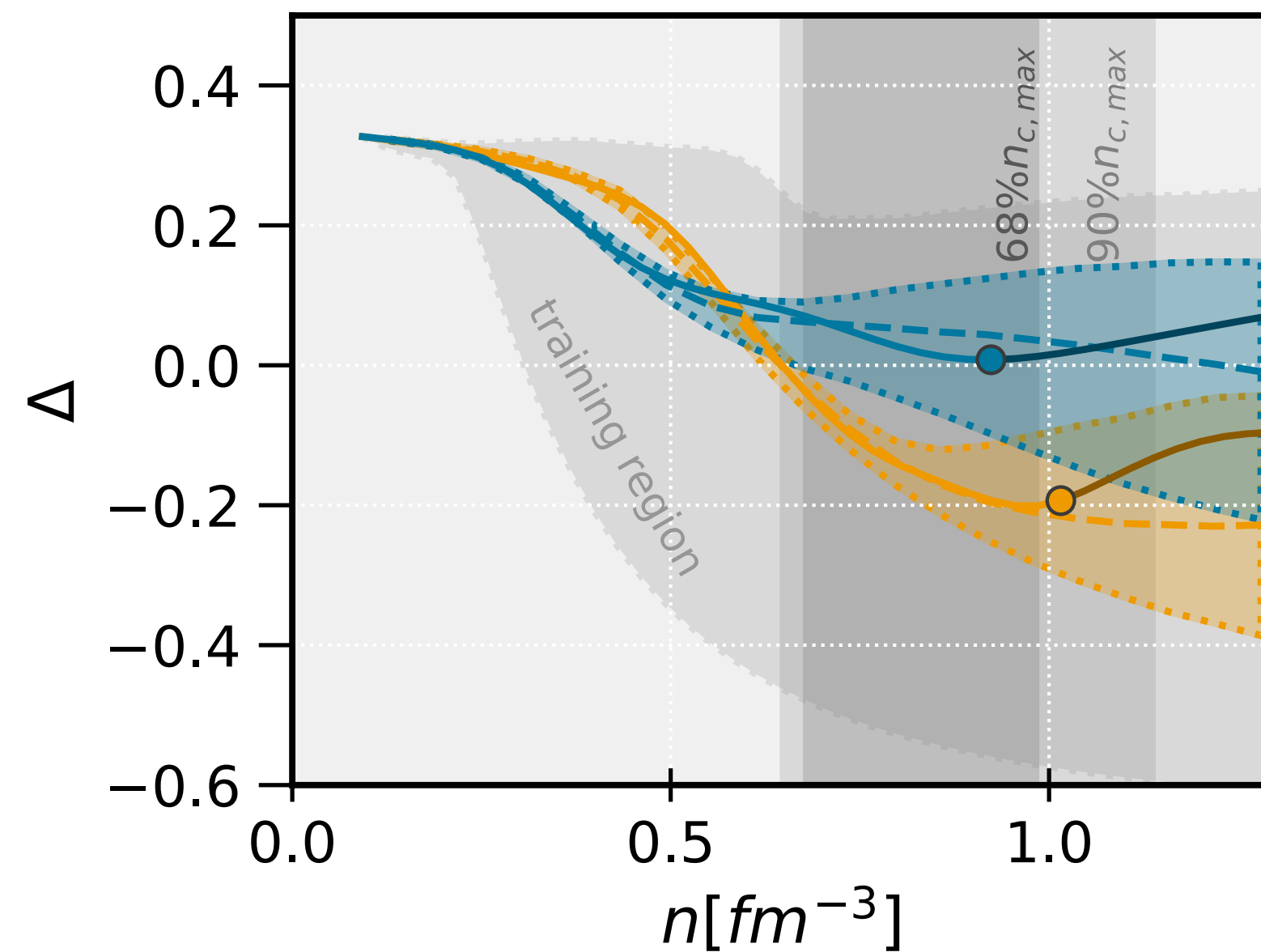
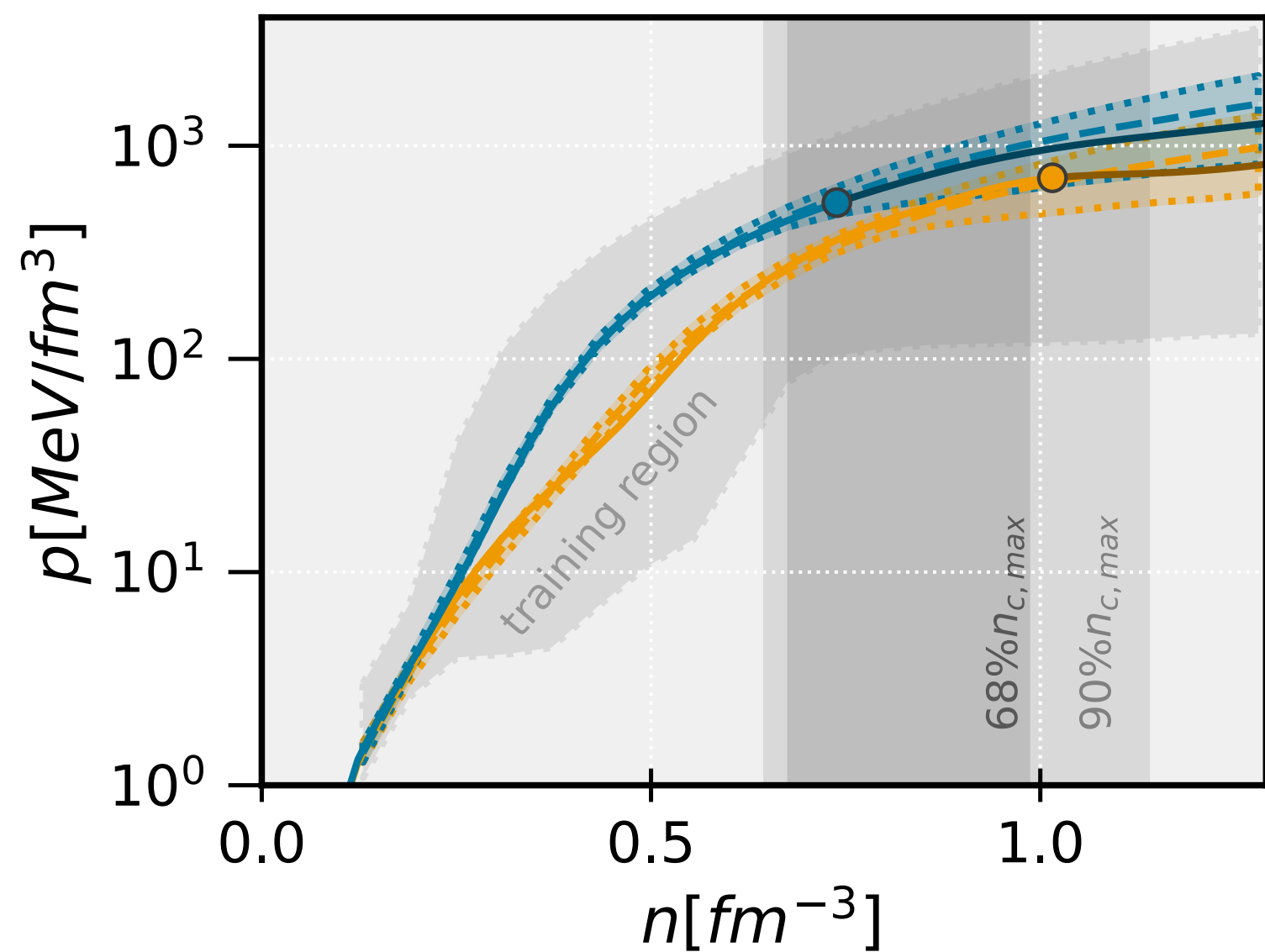
$$\begin{cases} R_x = [M_1, \dots, M_{15}, R_1, \dots, R_{15}], x \in [1,2] \\ R\Lambda_x = [M_1, \dots, M_{15}, R_1, \dots, R_{15}, M_1^*, \dots, M_{15}^*, \Lambda_1, \dots, \Lambda_{15}]. \end{cases}$$

$x = 1$ without noise, $x = 2$ with gaussian noise.



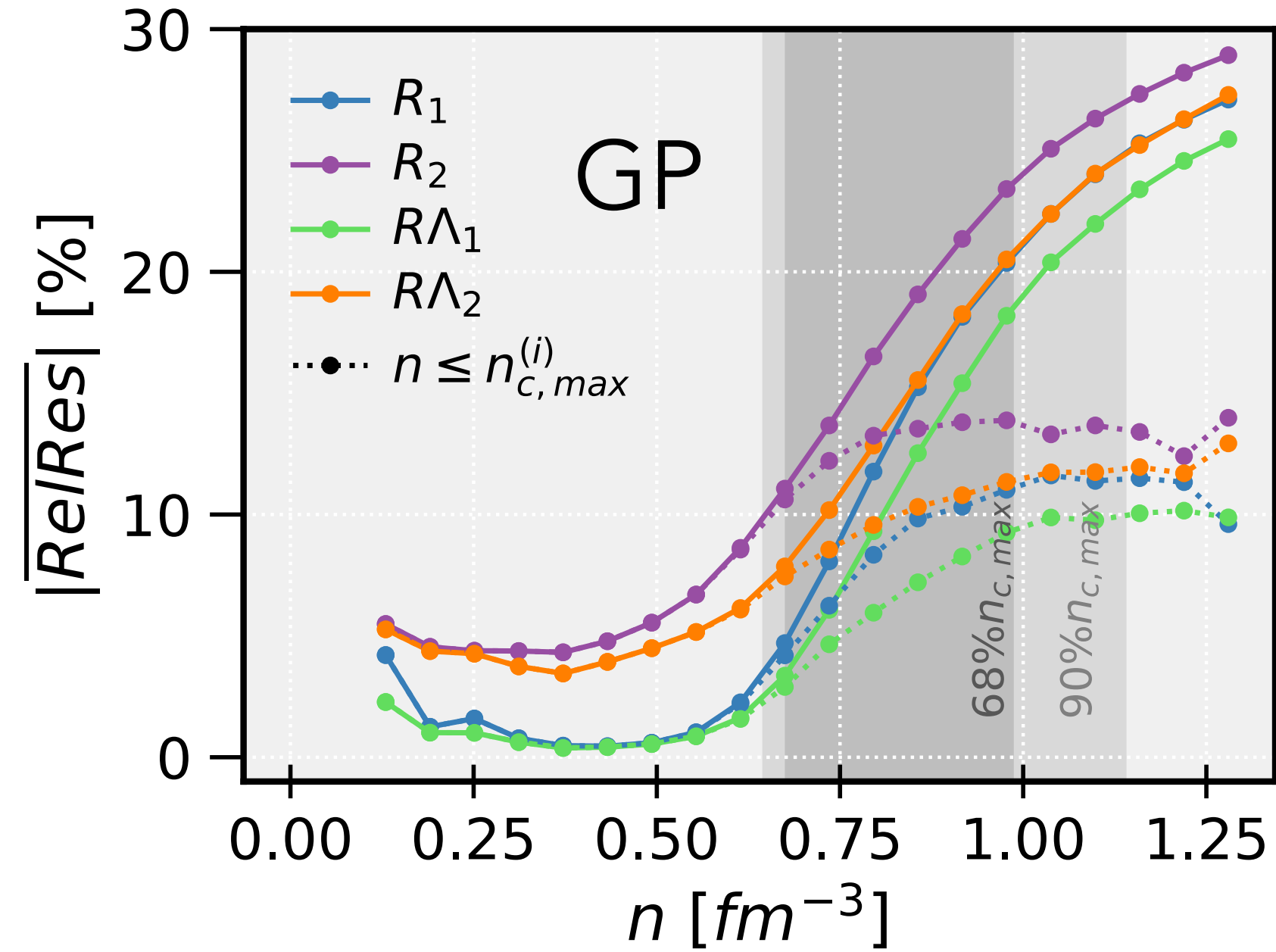
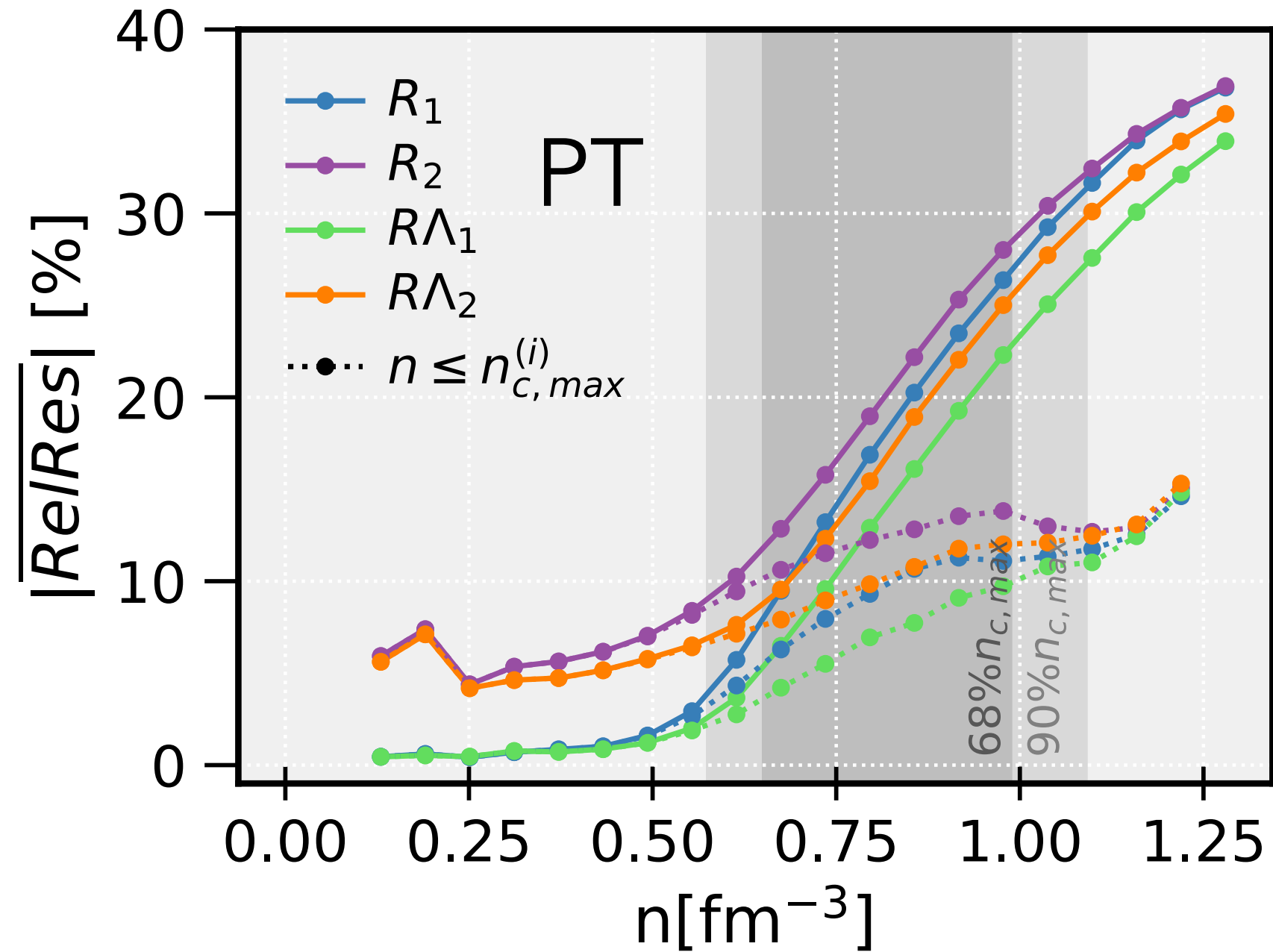
Key result: Accurate EoS reconstruction

- ▶ Prediction for 2 samples of the test set $R\Lambda_2$ —, with a 90 % CI  and median ,
- ▶ Increase in dispersion near maximum central density, represented by ,
- ▶ Predictions always inside the CI.



Just for GP dataset

Relative error for pressure



$$\text{RelRes}^{(i)}(n) = \text{Med}_l \left[\frac{X_p^{(i,l)}(n) - X_T^{(i)}(n)}{X_T^{(i)}(n)} \right] \times 100$$

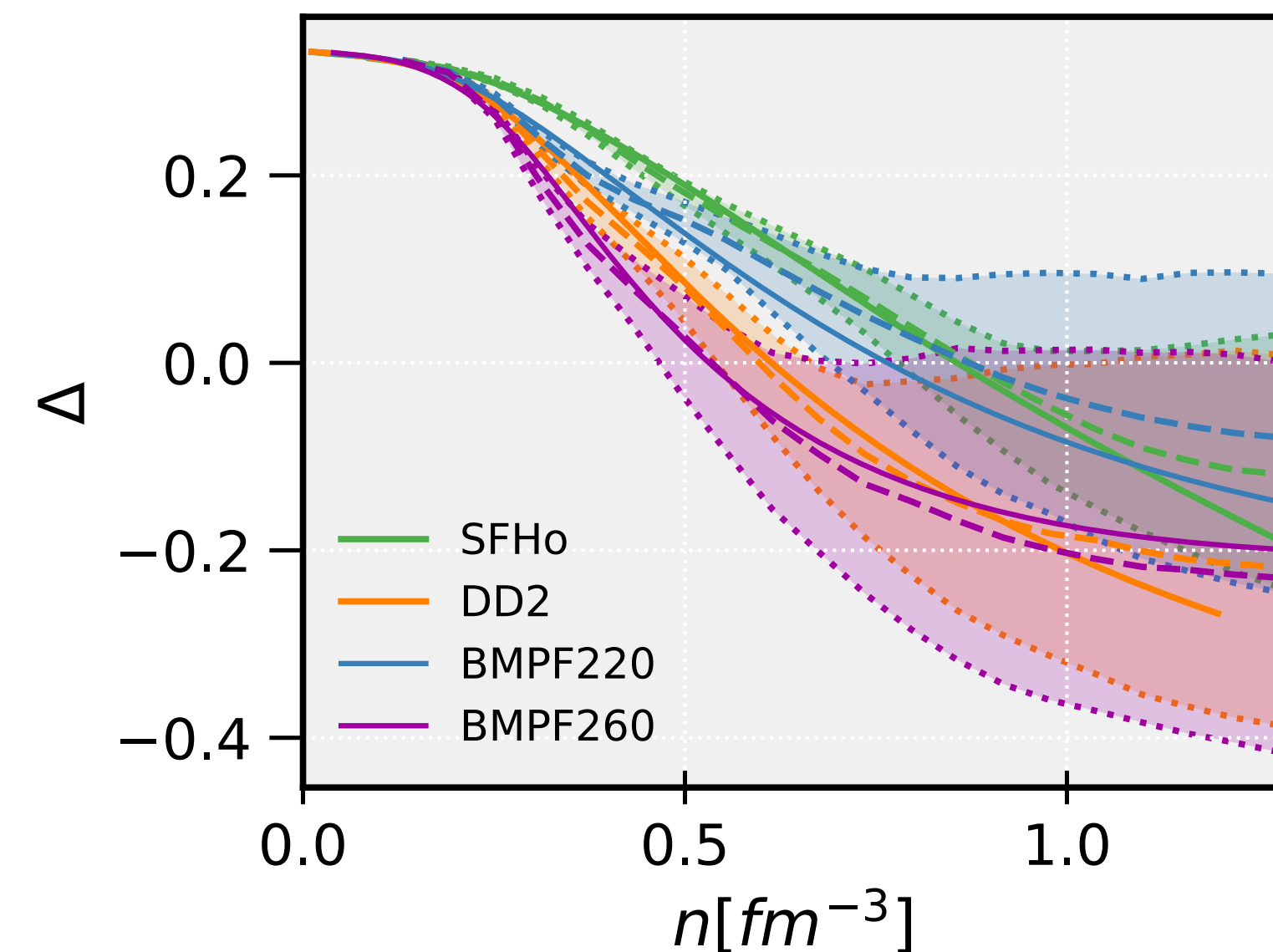
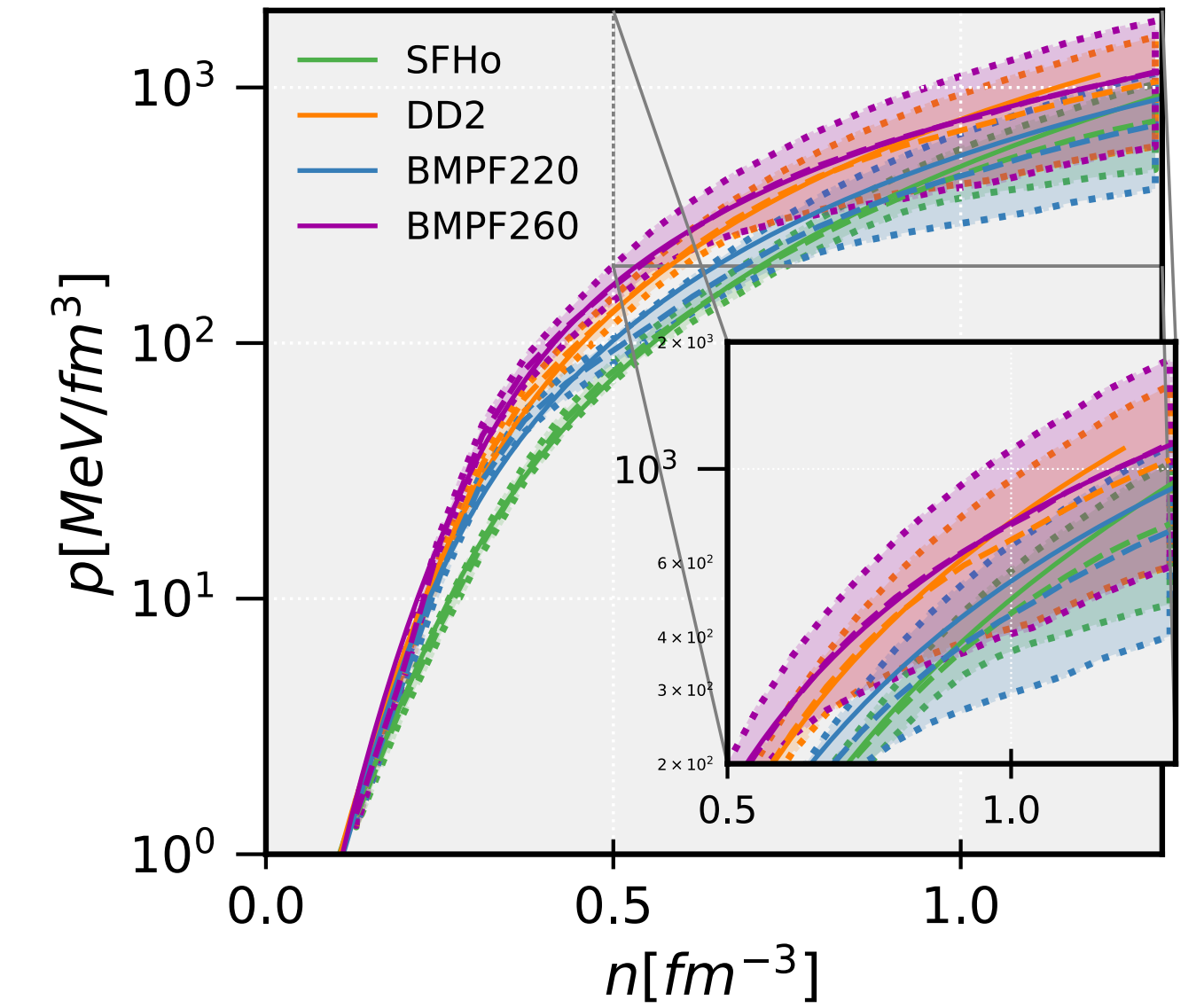
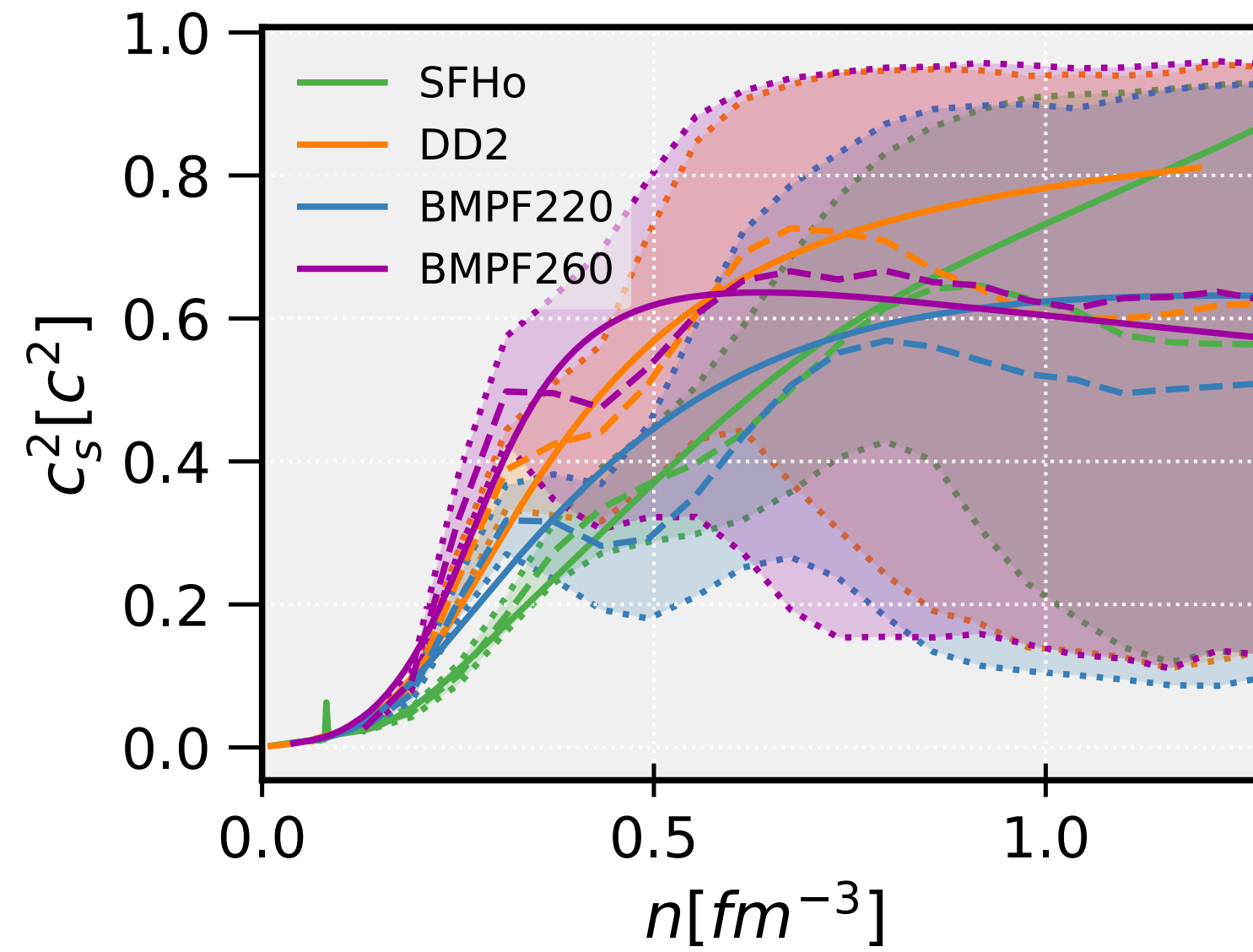
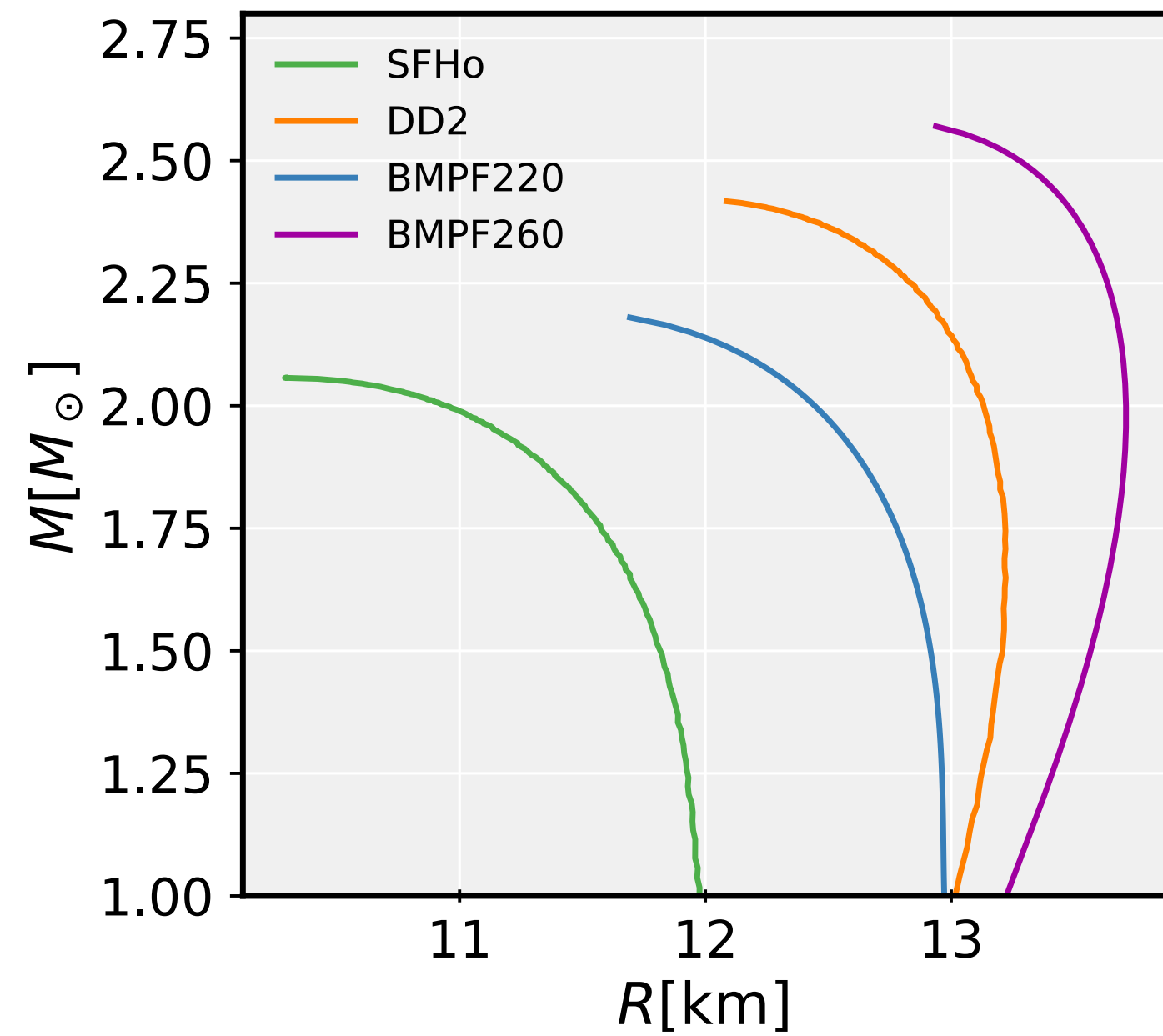
$$\begin{cases} |\overline{\text{RelRes}}|_{\leq n_{c,max}} = \text{Med}_i |\text{RelRes}^{(i)}(n)| & \text{for } n \leq n_{c,max}^{(i)} \\ |\overline{\text{RelRes}}| = \text{Med}_i |\text{RelRes}^{(i)}(n)| \end{cases}$$

- ▶ Error increases with noise,
- ▶ Error decreases with tidal deformability,
- ▶ Error decreases when filtered for $n_{c,max}$.

l = Posterior sample, i = EoS at density n

Another dataset inference test

- ▶ For the R_2 dataset we tested 4 EoS,
- ▶ Very different models.



Just for GP dataset

Summary

- ▶ Validation of neural posterior estimation,
 - ▶ Crucial role of tidal deformability,
 - ▶ Sensitivity to maximum central density,
 - ▶ Uncertainty quantification.
- ▶ **The outlook:** This method is well-suited for the upcoming “golden age” of multimessenger data, offering a promising tool to constrain dense matter physics.

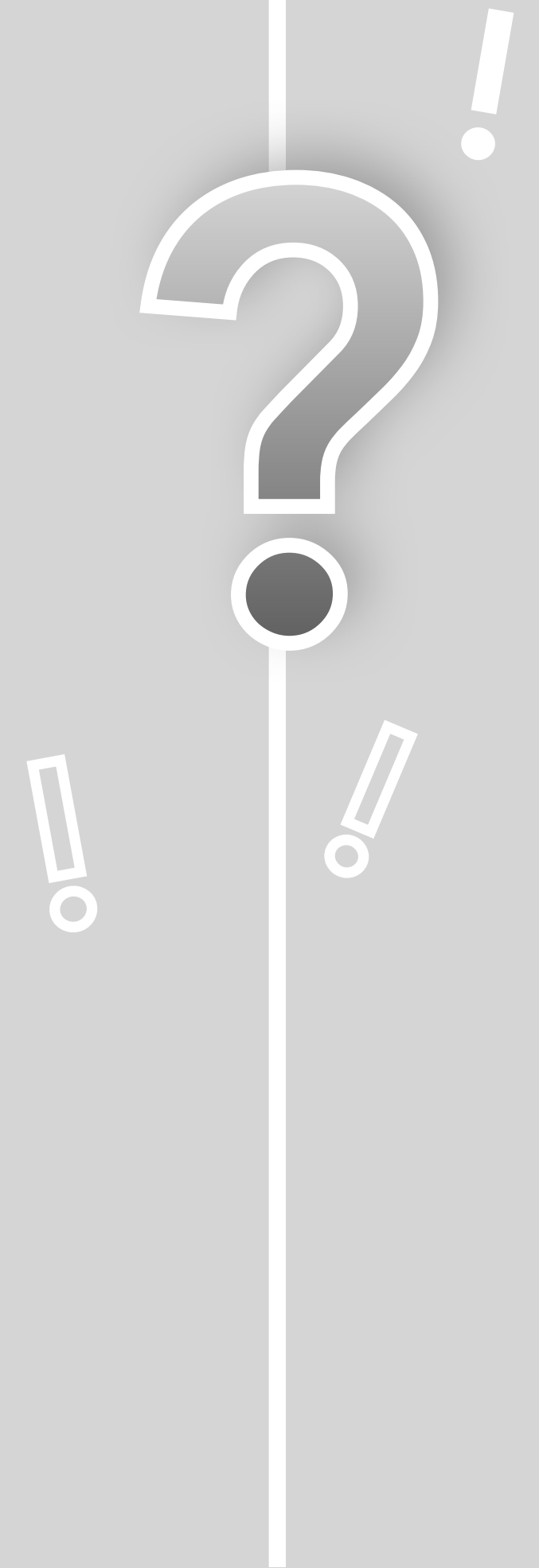
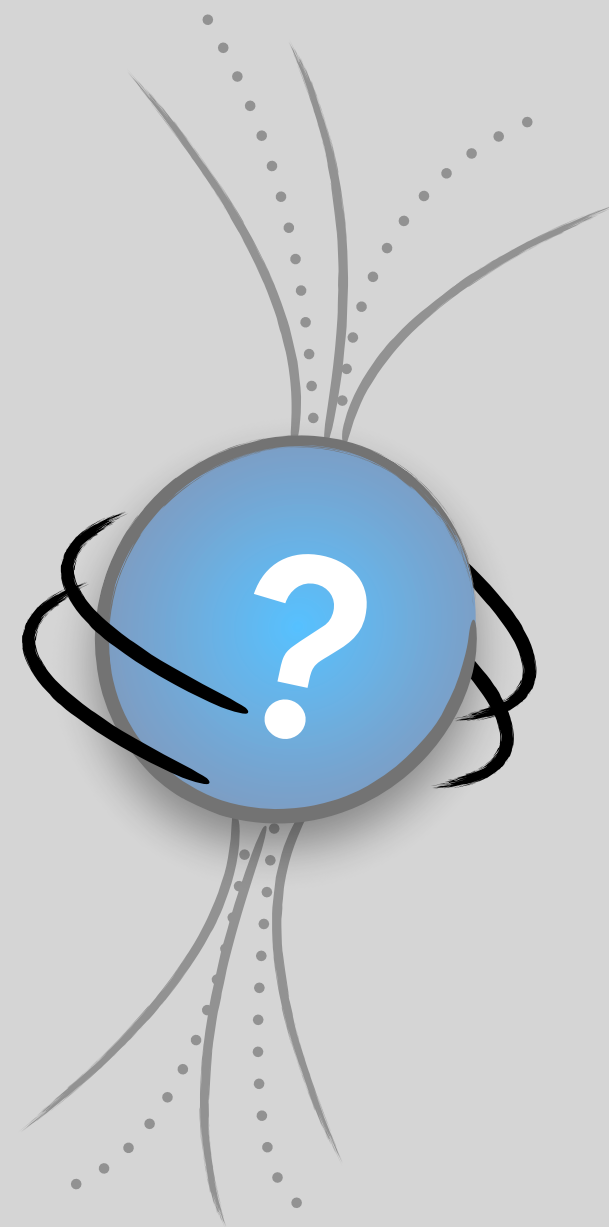
Still multiple open questions:

Do we have a phase transition?

What other particles do we have?

Do we have dark matter?

What is the particle fraction?



If you are curious about:

Understanding neutrons stars

+

machine learning



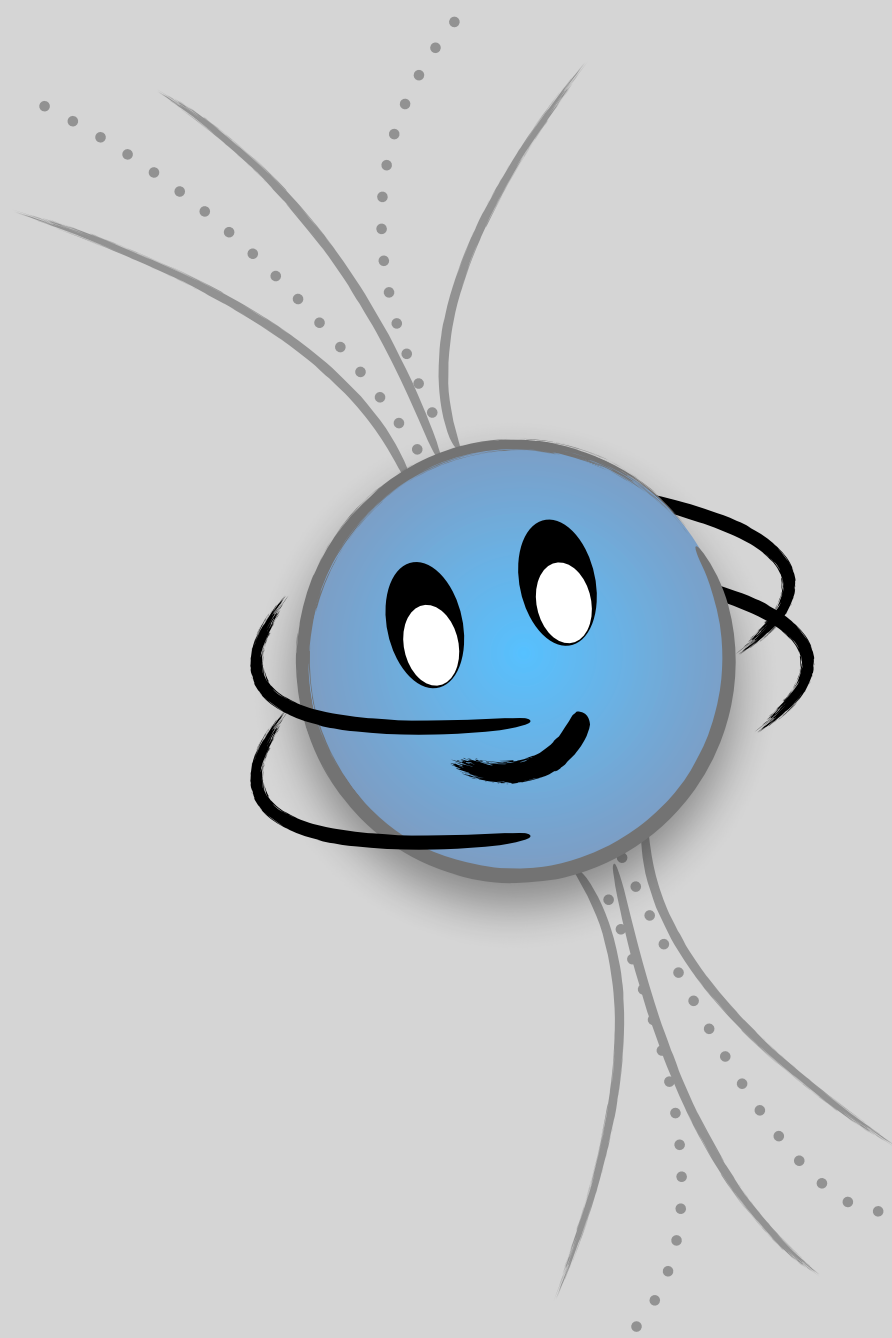
If you want to swim in these waters

or

dive deeper into the unknown.



= Summer research opportunities available for bachelor and master students 21



Thank you for your attention

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